

# Analytic Real-Time Analysis and Timed Automata: A Hybrid Method for Analyzing Embedded Real-Time Systems

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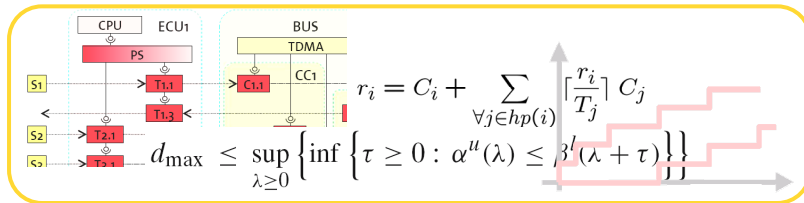
Artist-Design Cluster Meeting (Hardware Platforms)

Haus der Wissenschaft, Braunschweig, Germany, 26 June 2009



# Performance Analysis of Embedded Real-Time Systems

## Analytic Real-Time Analysis

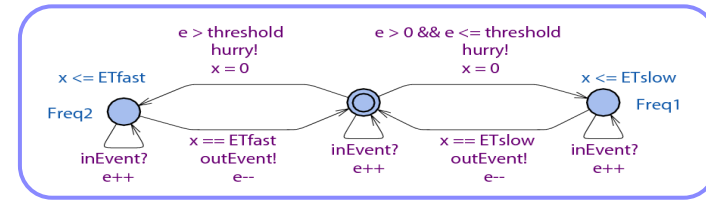


Solution of closed form expressions

Examples: RTC, SymTA/S, MAST, ...

- + Good scalability
- + Fast analysis
- Limited to few specific measures (e.g. delays, buffer sizes)
- Systems restricted to specific models
- Overly conservative results

## State-based Real-Time Analysis



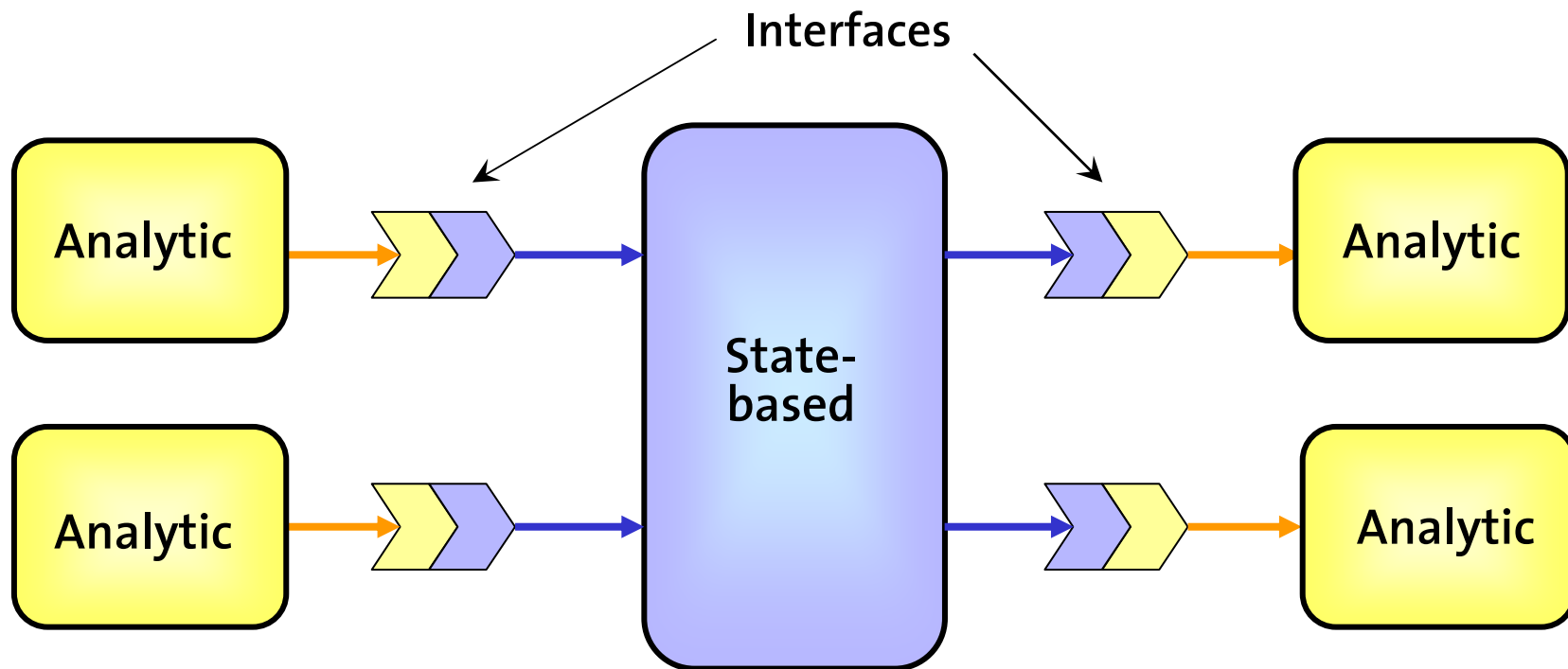
Model checking of properties

Examples: Timed Automata (TA), FSM, ...

- Poor scalability
  - Slow verification
- } State space explosion
- + Verification of functional and non-functional properties
  - + Modeling power
  - + Exact results

# New Compositional Framework for Hybrid Analysis

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# Motivation for Hybrid Approach

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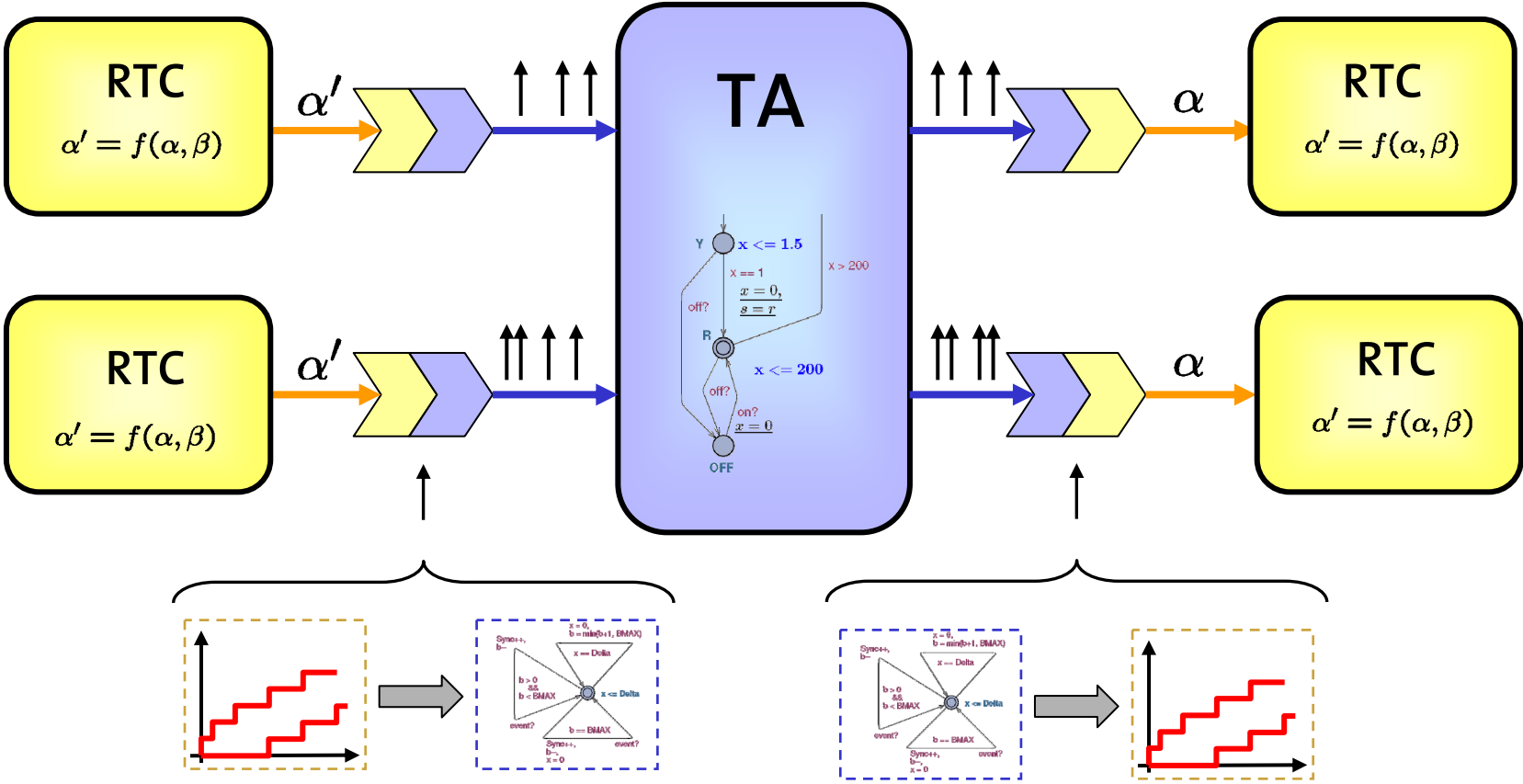
1. The obtained performance metrics are not destructively over-approximated

(Tighter analysis results compared to purely analytical abstraction)

2. The problem of state space explosion is limited to the level of isolated components

(Faster verification compared to purely state-based models)

# Interfacing Real-Time Calculus and Timed Automata



# Contributions

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- Pattern for conversion of abstract event stream models (such as PJD or arrival curves) to a network of cooperating TA
- Proof of correctness and completeness
- Pattern for derivation of abstract event stream models from a TA-based system model
- Implementation and Case Study

# Related work

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- **Event Count Automata**

L. T. X. Phan, S. Chakraborty, P. S. Thiagarajan, and L. Thiele. *Composing functional and state-based performance models for analyzing heterogeneous real-time systems*. In Proc. of the 28th IEEE Real-Time Systems Symposium (RTSS 2007), pages 343–352. IEEE Computer Society, 2007.

- **CATS Tool**

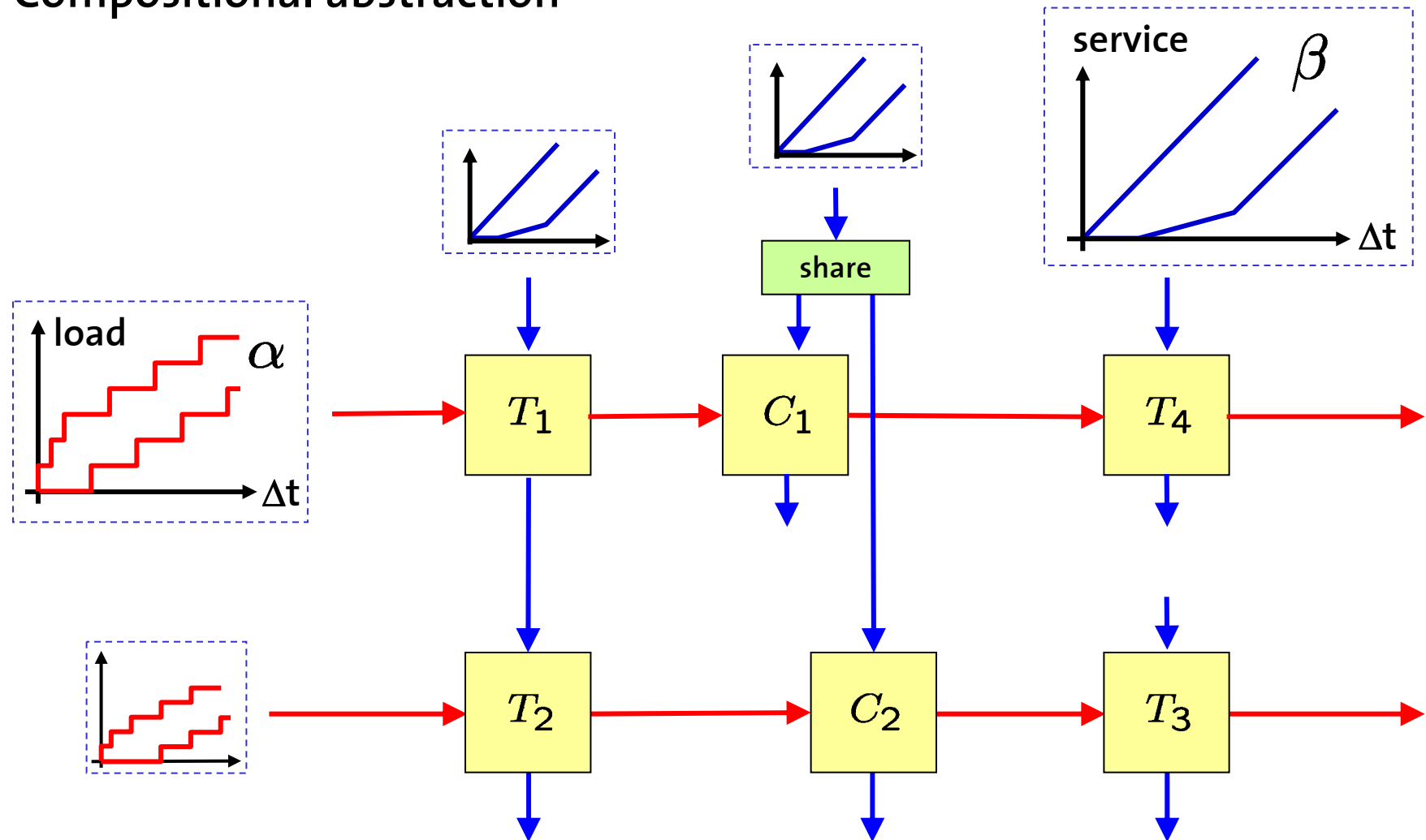
P. Krcal, L. Mokrushin, and W. Yi. *A tool for compositional analysis of timed systems by abstraction* (extended abstract). In Proc. of NWPT07, the 19th Nordic Workshop on Programming Theory, October 2007.

- **Efficient Model-Checking for Real-Time Task Networks**

H. Dierks, A. Metzner, and I. Stierand. *Efficient Model-Checking for Real-Time Task Networks*. In Int. Conf. on Embedded Software and Systems 2009. Accepted for publication.

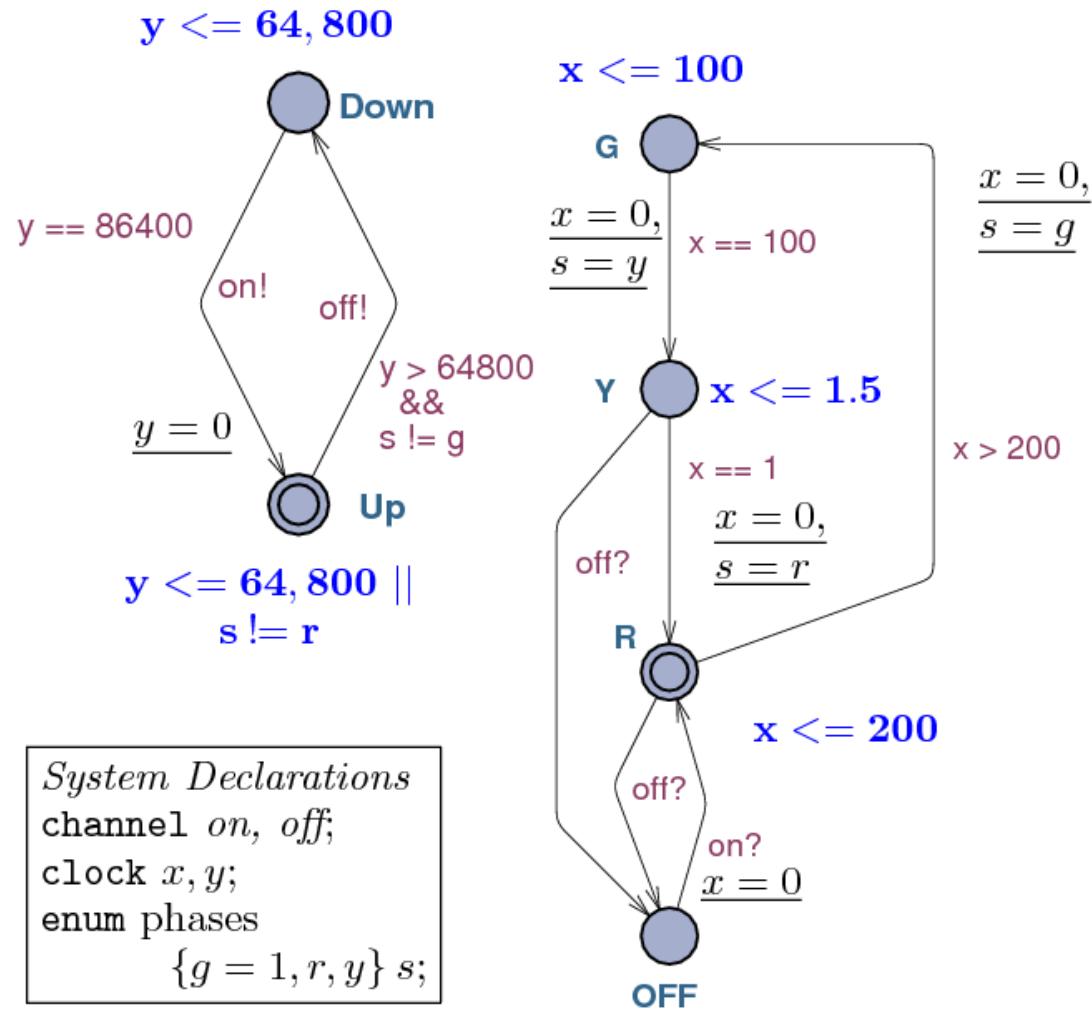
# Real-Time Calculus (RTC)

## Compositional abstraction

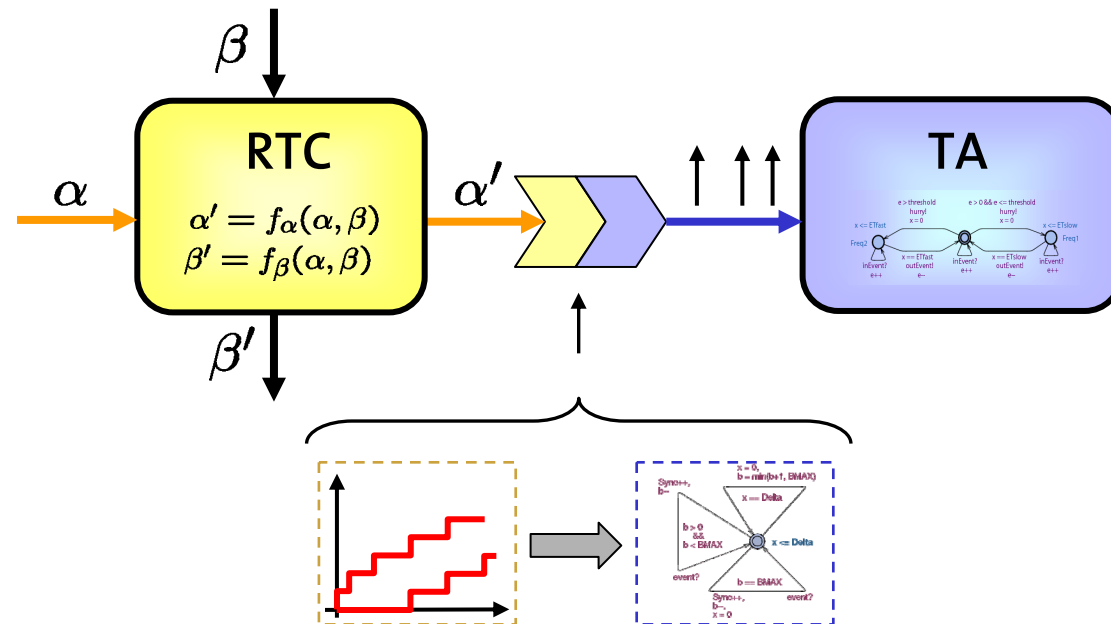




# Timed Automata (TA)



# Interface RTC → TA



How to represent arrival curves as TA?

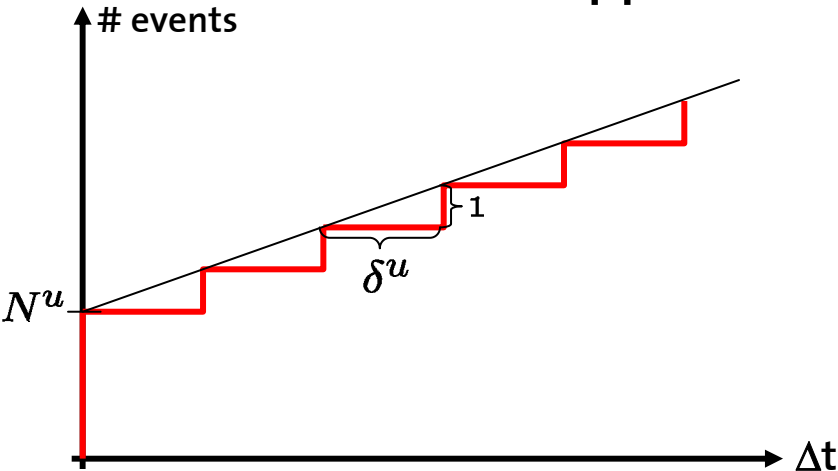
# Principle

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1. Decompose arrival curves to set of simpler curve components  
→ Set of linear staircase functions
2. Represent each curve component as TA (Leaky Bucket pattern)  
→ Set of simple TA
3. Synchronize all TA such to obtain same event stream model as described by arrival curve  
→ Network of synchronized TA

# Linear arrival curves

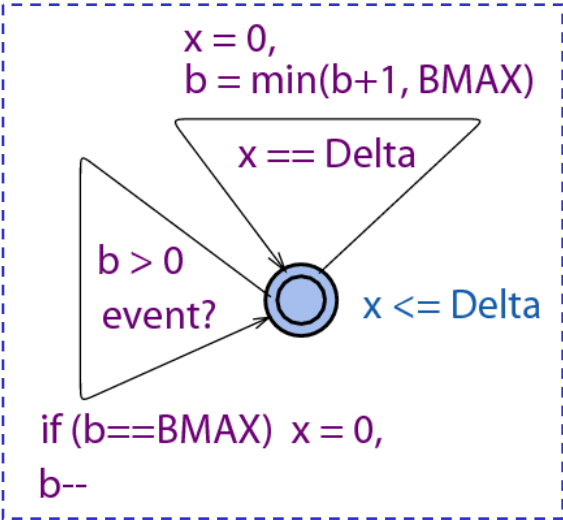
## Upper arrival curve



$$\alpha^u(\Delta) = N^u + \left\lceil \frac{\Delta}{\delta^u} \right\rceil$$

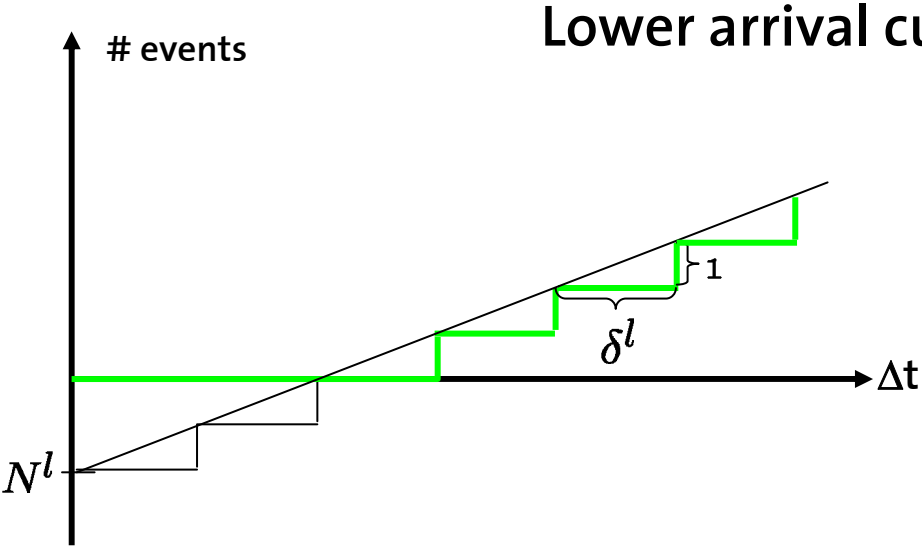


Max fill level:  $N^u$   
 Fill rate:  $1/\delta^u$   
 Event emission allowed if fill level  $> 0$



Automaton for linear upper arrival curve (UTA)

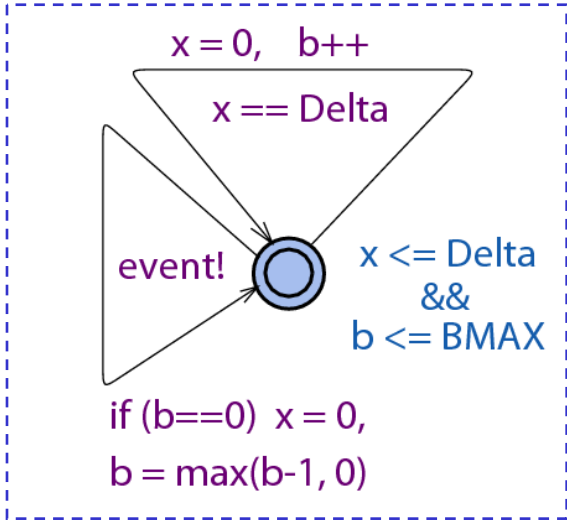
# Linear arrival curves



$$\alpha^l(\Delta) = \max \left\{ 0, N^l + \left\lfloor \frac{\Delta}{\delta^l} \right\rfloor \right\}$$



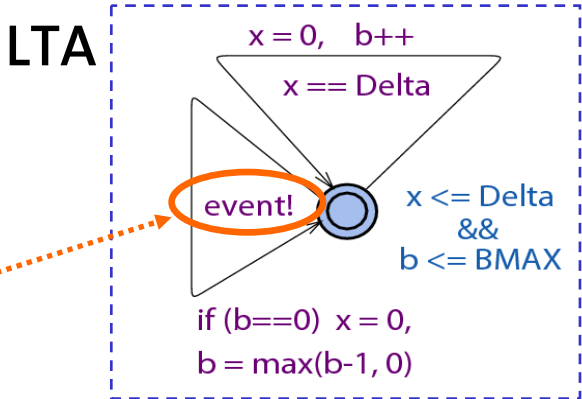
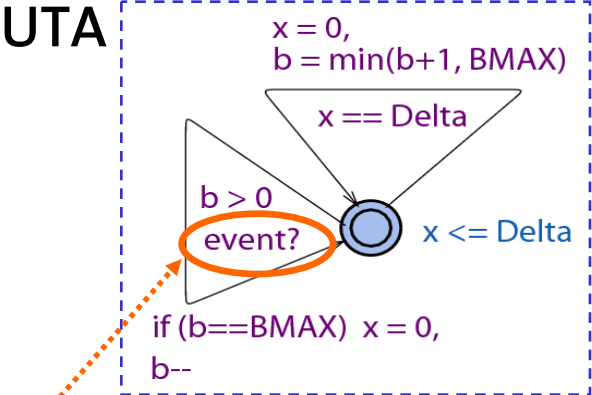
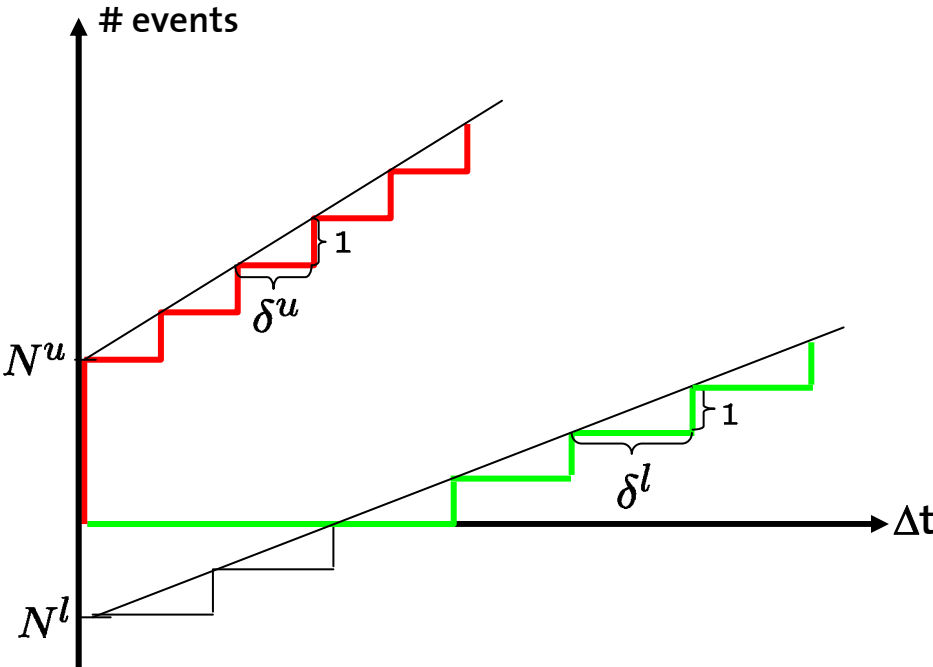
Max fill level:  $|N^l|$   
 Fill rate:  $1/\delta^l$   
 Event emission enforced if maximum fill level reached



Automaton for linear lower arrival curve (LTA)

# Linear arrival curves

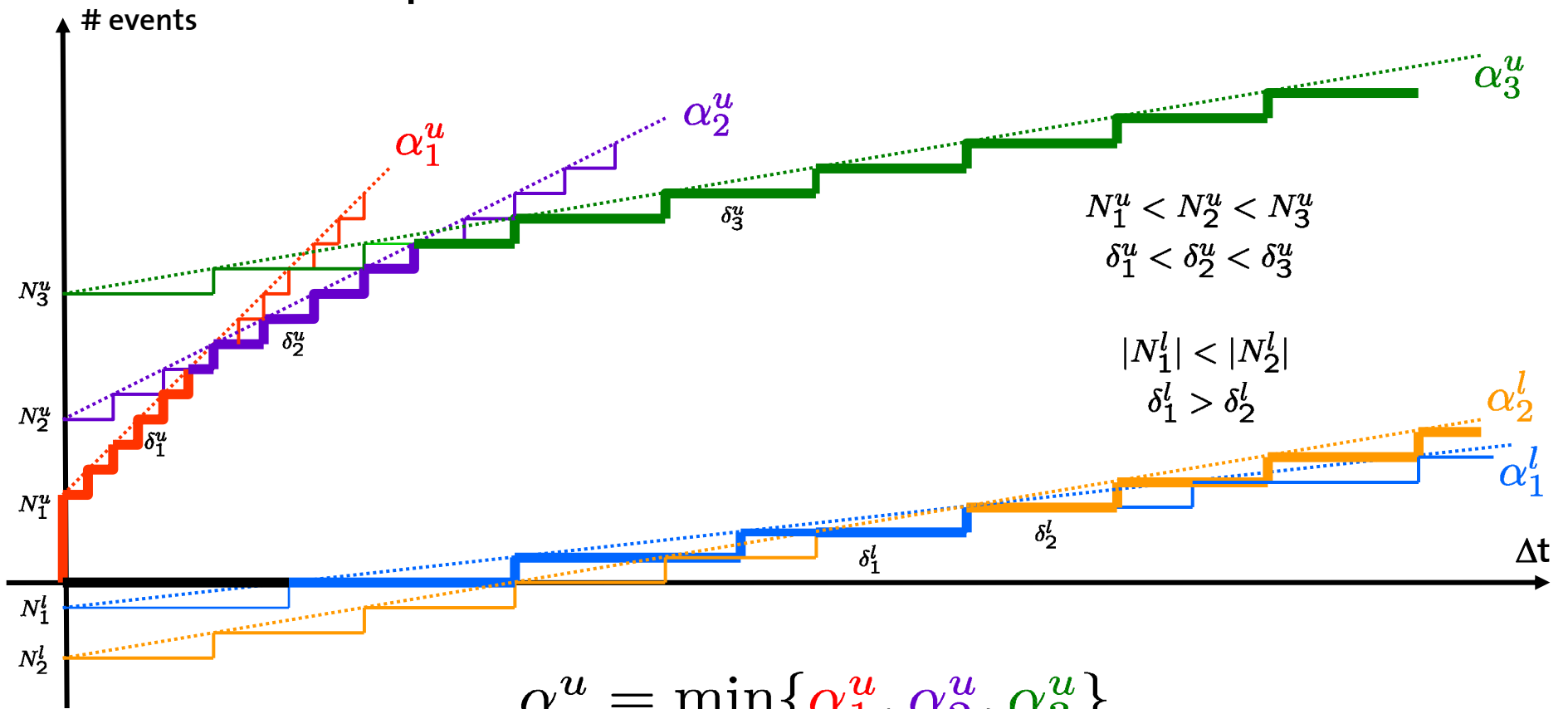
## Combination of lower and upper arrival curves



Synchronization

# Convex and concave patterns

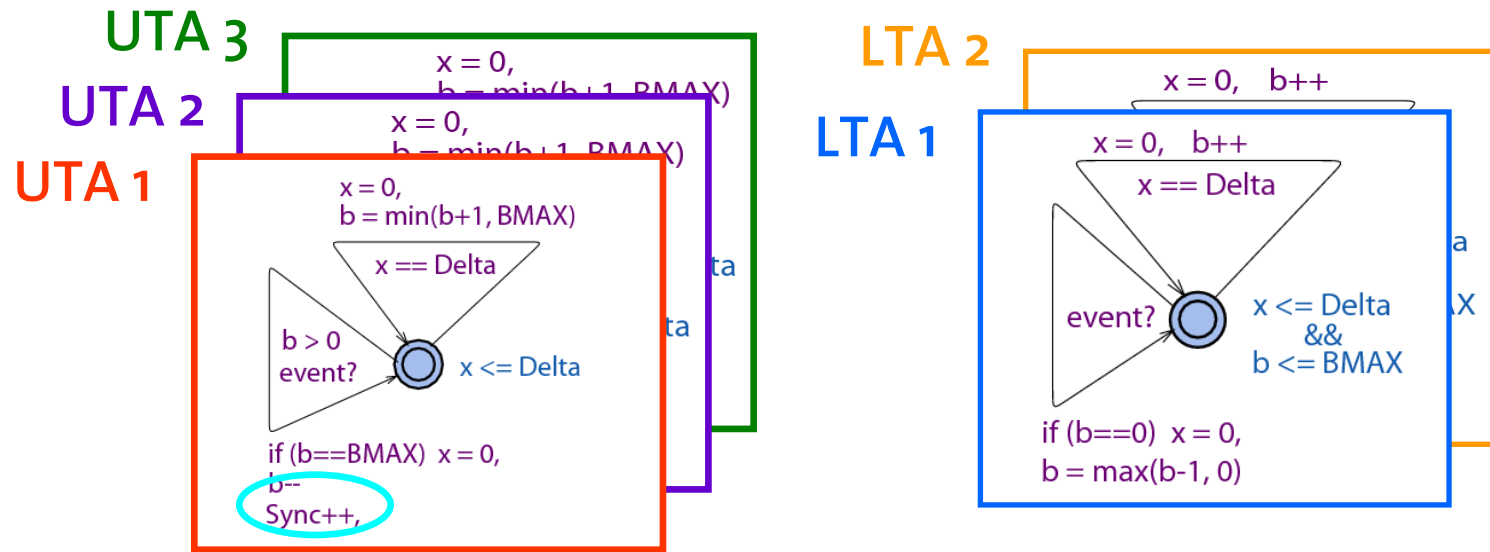
## Composition of linear staircase functions



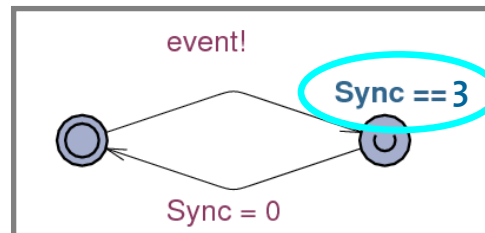
$$\alpha^u = \min\{\alpha_1^u, \alpha_2^u, \alpha_3^u\}$$

$$\alpha^l = \max\{0, \alpha_1^l, \alpha_2^l\}$$

# Convex and concave patterns



Scheduler



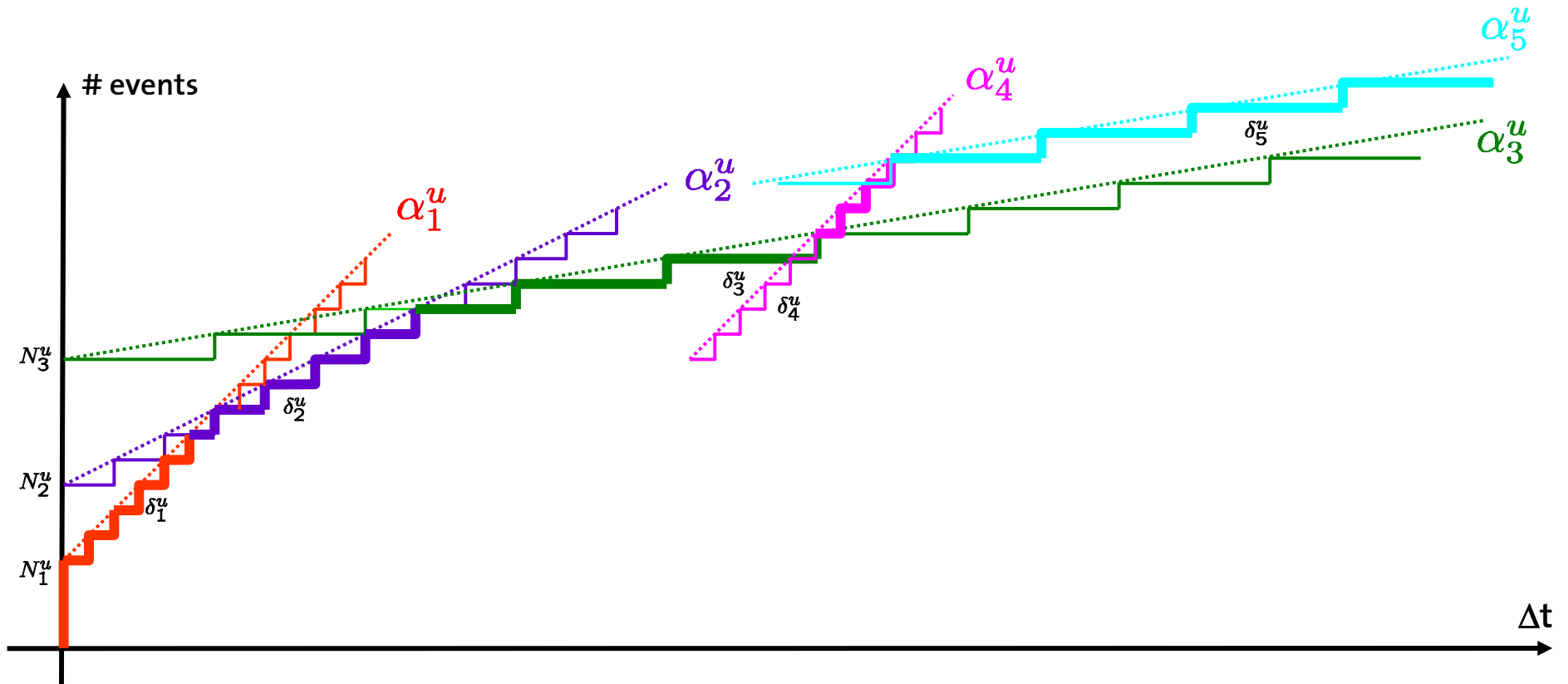
broadcast chan event

- Event generation only if all UTA permit it (AND composition)
- Single LTA can enforce event generation (OR composition)



# General arrival curves

How to represent non-convex/concave patterns?

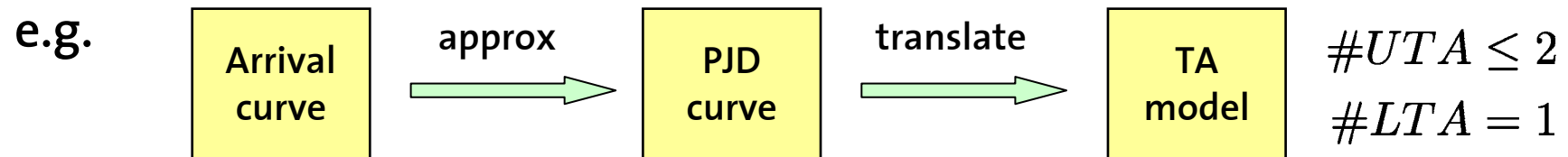


Use min/max operators locally on subsets of UTA/LTA

# Complexity

Run-time of verification increases exponentially with number of clocks

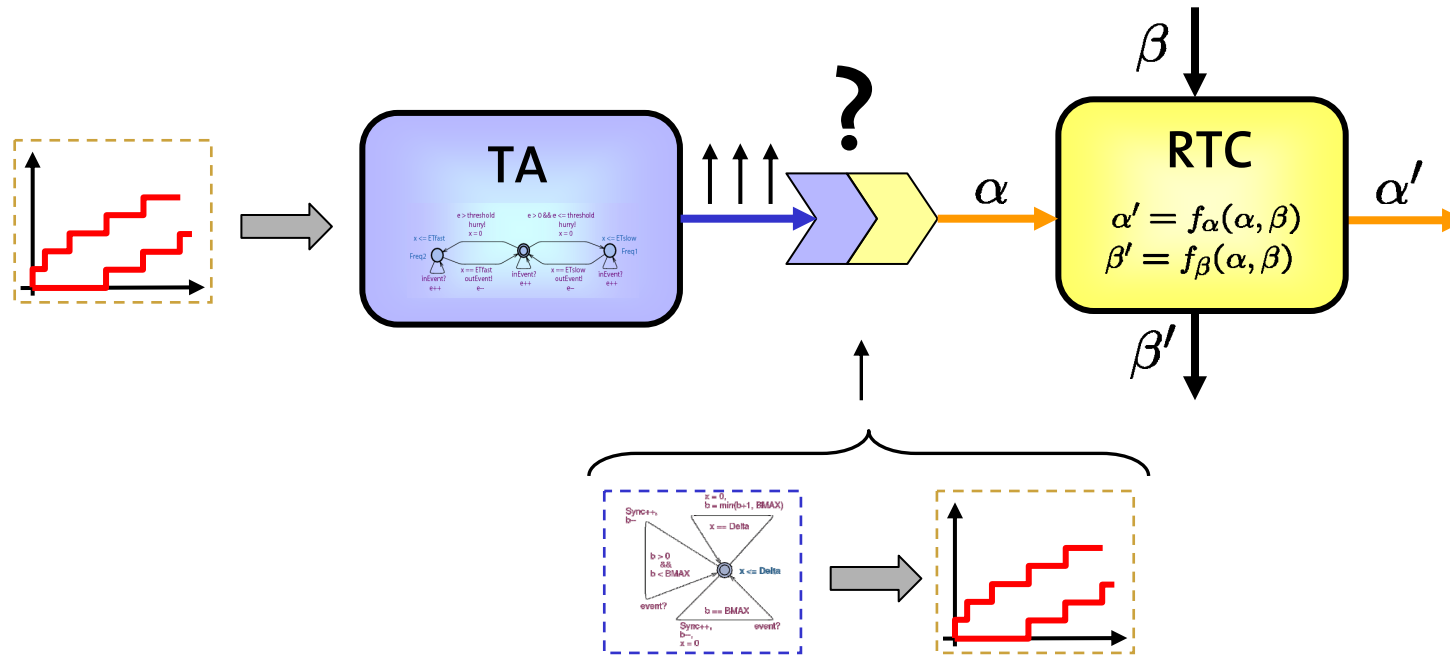
→ Approximate arrival curves with few staircase functions



$$d = 0 \vee d \leq p - j : \quad N^u = \left\lceil \frac{j}{p} \right\rceil + 1; \quad N^l = \left\lceil \frac{j}{p} \right\rceil; \quad \delta^u = \delta^l = p$$

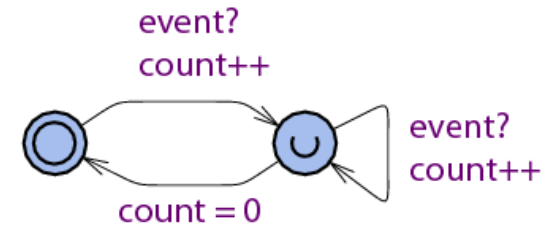
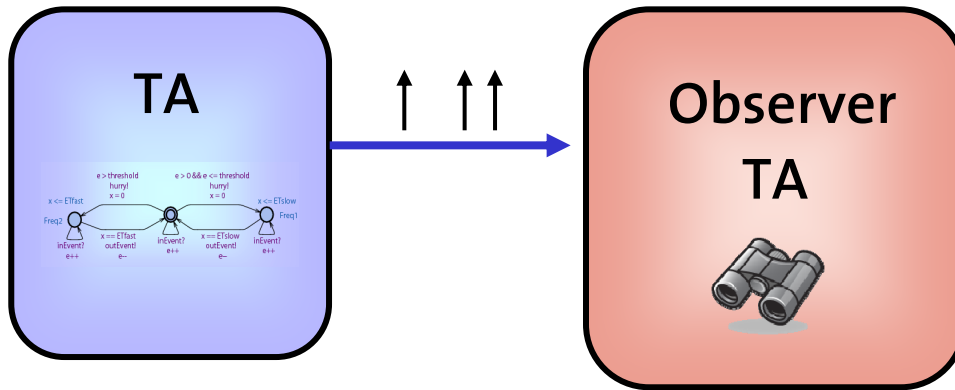
$$d > 0 \wedge d > p - j : \quad N_1^u = 1; \quad \delta_1^u = d; \quad N_2^u = \left\lceil \frac{j}{p} \right\rceil + 1$$
$$N^l = \left\lceil \frac{j}{p} \right\rceil; \quad \delta_2^u = \delta^l = p$$

# Interface TA → RTC



How to derive output arrival curves from a TA sub-system model?

# Interface TA $\rightarrow$ RTC

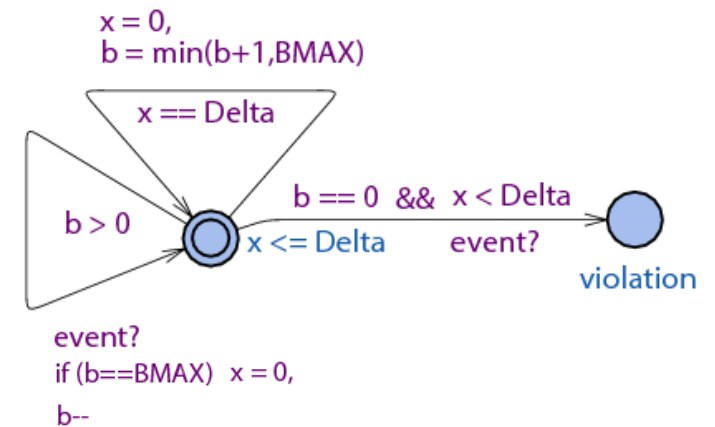
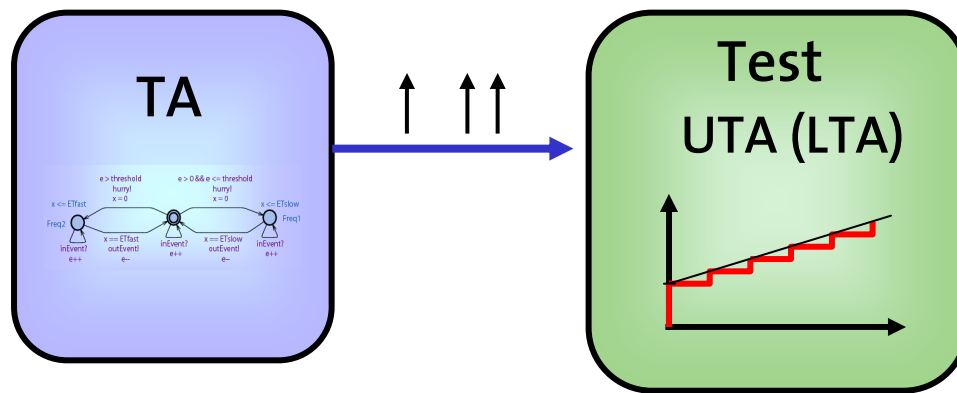


Verify

$A []$  (count  $\leq$  estimate)

Key parameters of curve (e.g. max burst) are determined by appropriate observer TA and binary search

# Interface TA $\rightarrow$ RTC



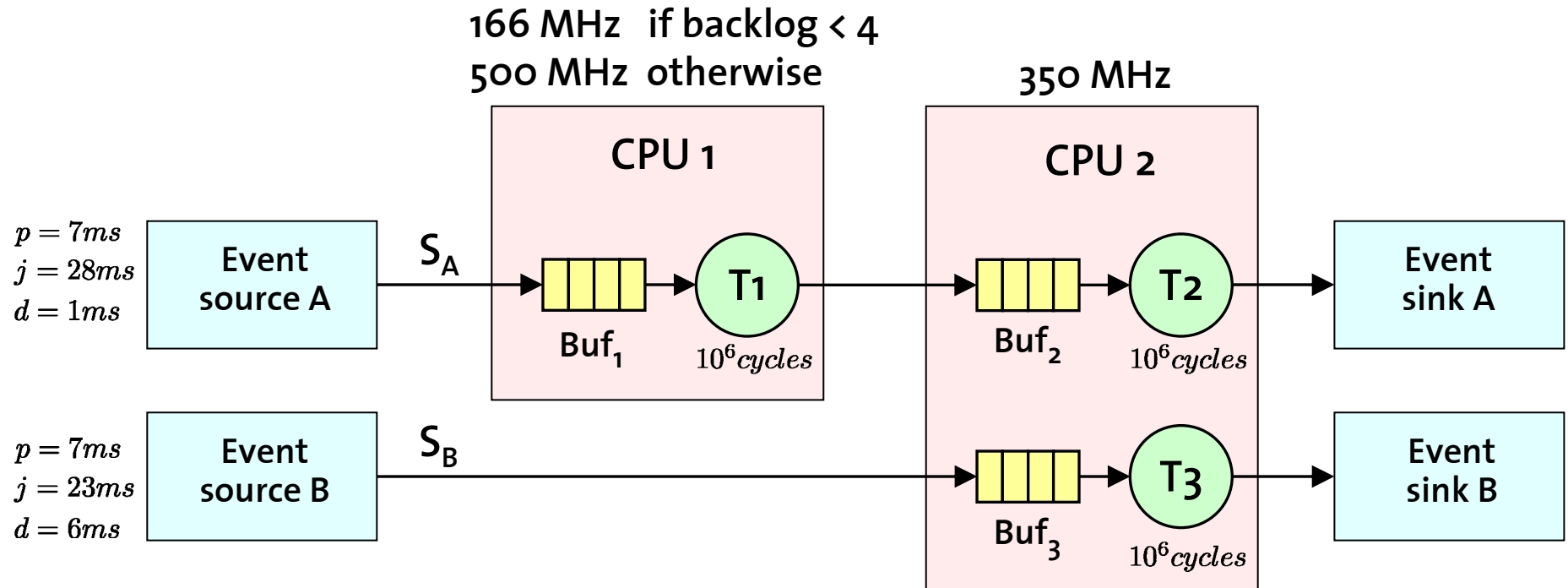
**Verify**  
(A [] (not violation))

- Verify compliance of system output with a number of UTA ( $N_i, \delta_i$ ) and LTA ( $N_i, \delta_i$ ) (Search strategy: Fix one parameter and modify the other by binary search)
- Combine obtained linear staircase functions by min and max operators

→ Yields convex/concave approximation of system output

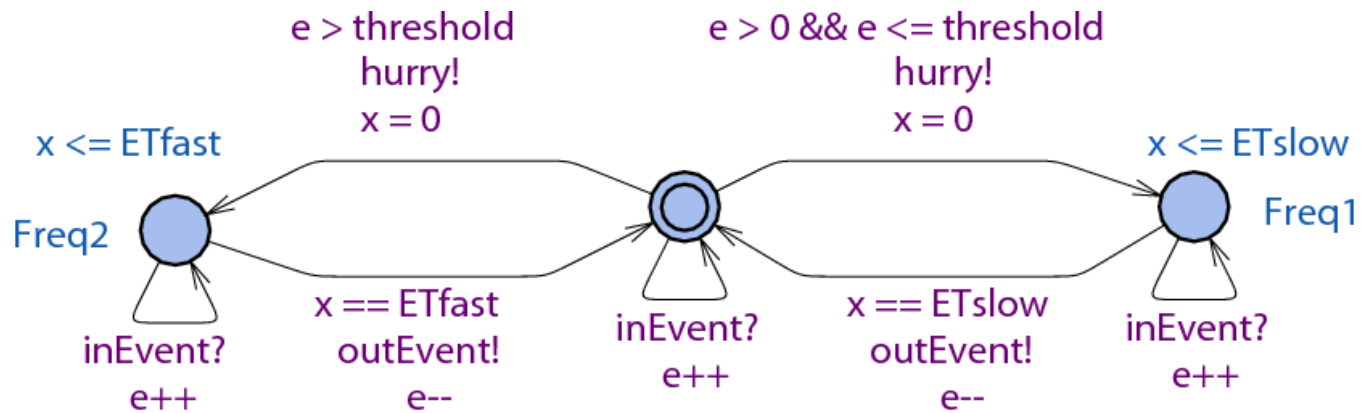
# Case Study

## CPU1: Load-dependent frequency adaptation



- Characterize output of T<sub>1</sub>
- Determine delays and required buffer sizes

# Case Study

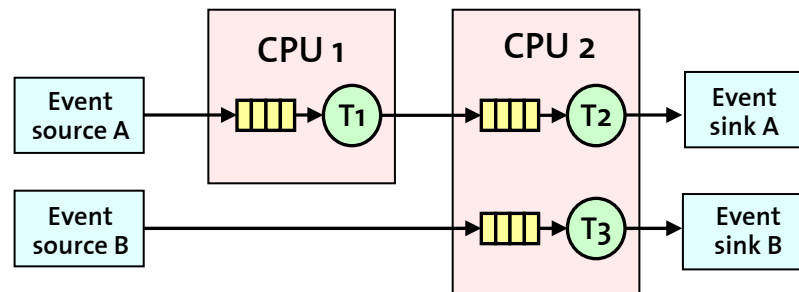


TA model for CPU1

# Case Study

## Results of performance analysis

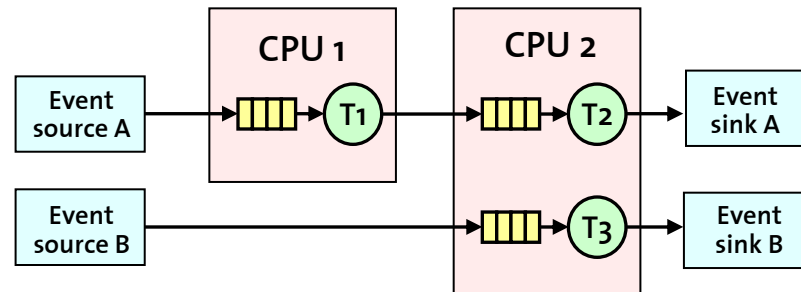
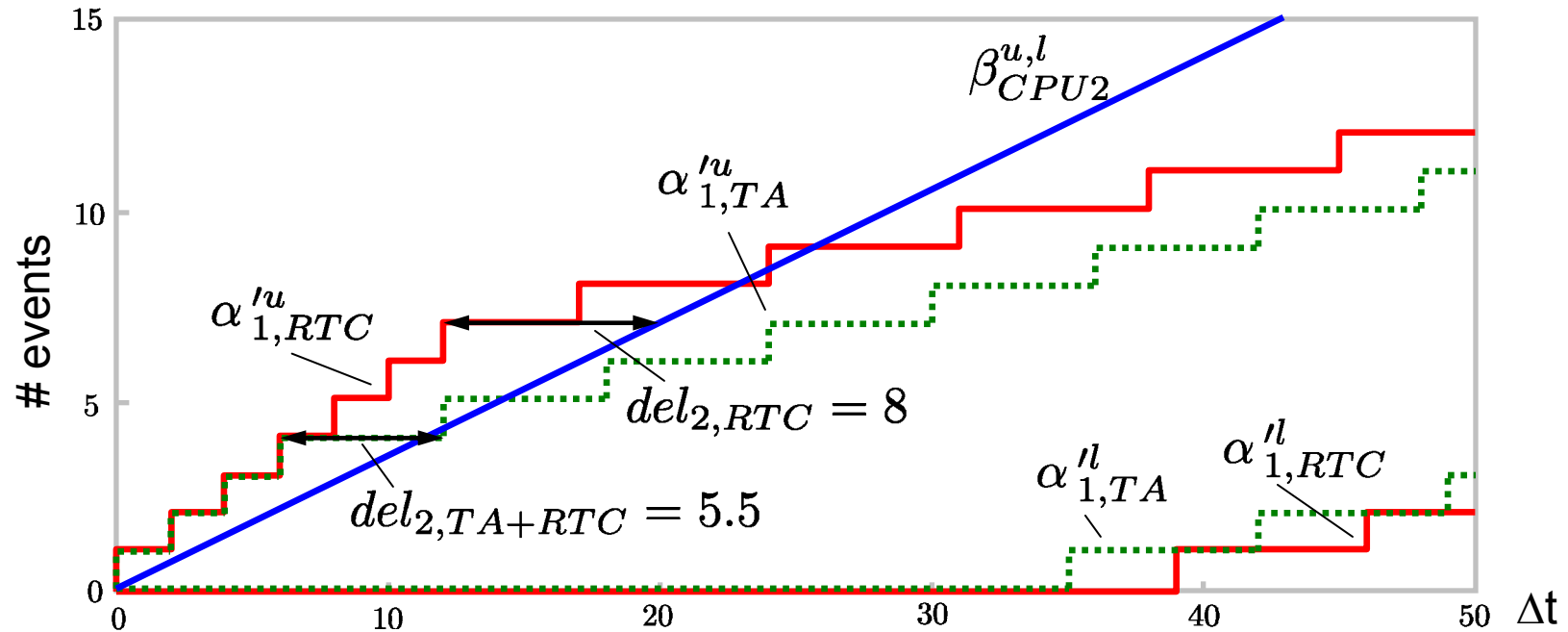
	Max delay [ms]				Max buffer [events]		
	T <sub>1</sub>	T <sub>2</sub>	T <sub>3</sub>	EE <sub>A</sub>	T <sub>1</sub>	T <sub>2</sub>	T <sub>3</sub>
RTC	29	8	28.6	31.9	5	3	5
TA + RTC	25	5.5	17.2	30.5	5	2	3
TA	25	4.6	14.3	27.9	5	2	3





# Case Study

## Delay computation for T2



# Case Study

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## Results of performance analysis

	Max delay [ms]				Max buffer [events]		
	T <sub>1</sub>	T <sub>2</sub>	T <sub>3</sub>	EE <sub>A</sub>	T <sub>1</sub>	T <sub>2</sub>	T <sub>3</sub>
RTC	29	8	28.6	31.9	5	3	5
TA + RTC	25	5.5	17.2	30.5	5	2	3
TA	25	4.6	14.3	27.9	5	2	3

## Run-times

	RTC	TA + RTC	TA
Total run-time	< 1s	11min	1h

# Conclusions

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- Hybrid and compositional analysis method that couples analytical approach (RTC) with state-based approach (TA)
- Permits to trade off analysis accuracy against verification time
- Key principle: Represent arrival curves by min/max of linear staircase functions