

# Influence of different system abstractions on the performance analysis of distributed real-time systems

TRESOR seminar, EPFL Lausanne

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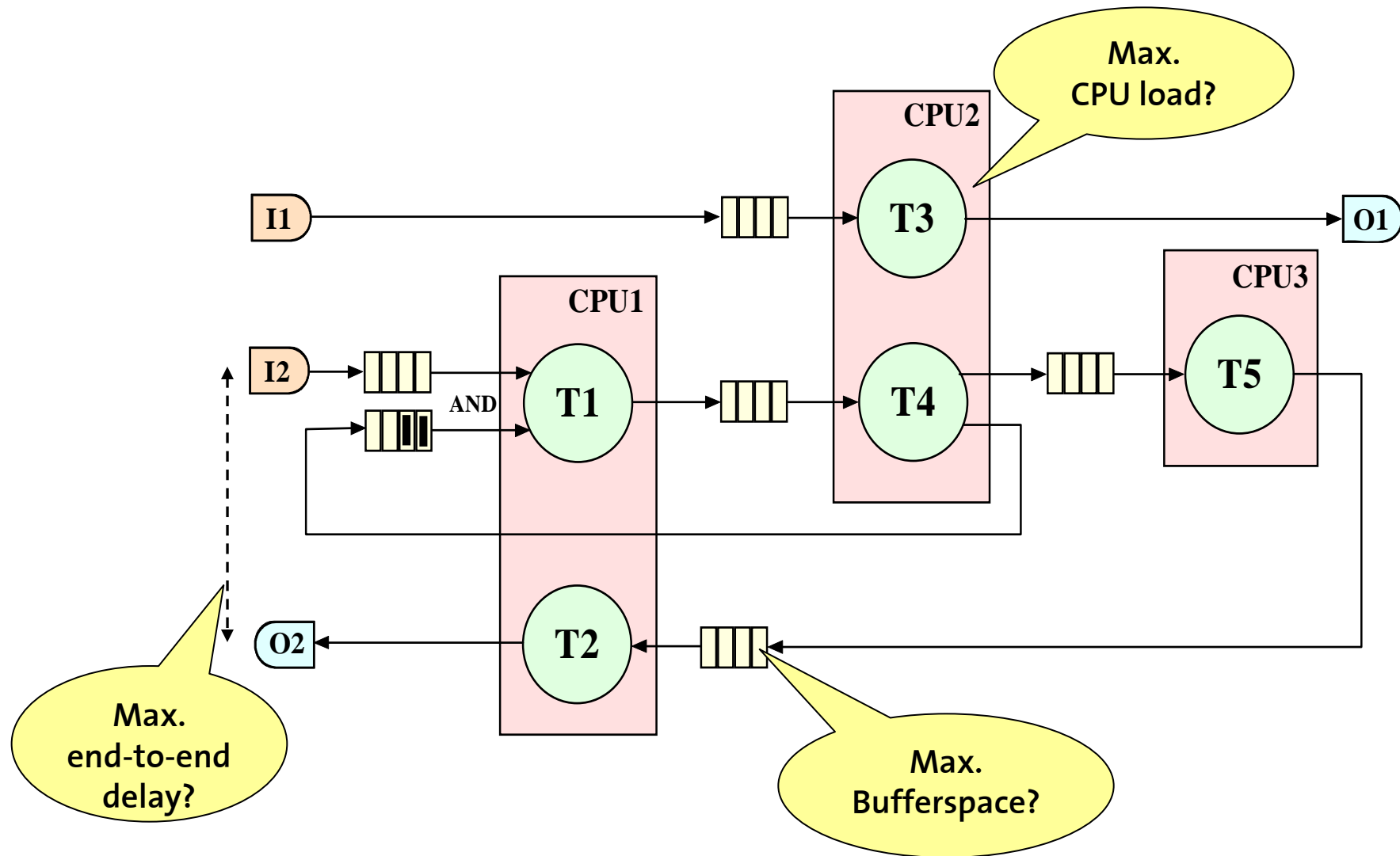
Computer Engineering and Networks Laboratory  
ETH Zürich, Switzerland

# Outline

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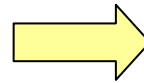
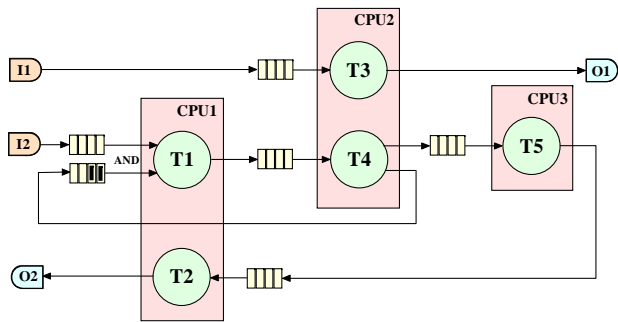
- Motivation
- Abstractions
- Benchmarks
- Conclusions

# System level performance analysis



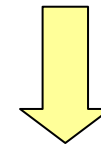
# Formal analysis methods

## Distributed system

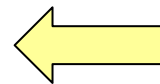
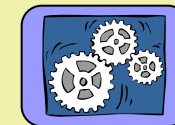


## Abstraction 3

$$r_i = C_i + \sum_{\forall j \in hp(i)} \lceil \frac{r_i}{T_j} \rceil C_j$$



## Analysis method 3



## Performance values



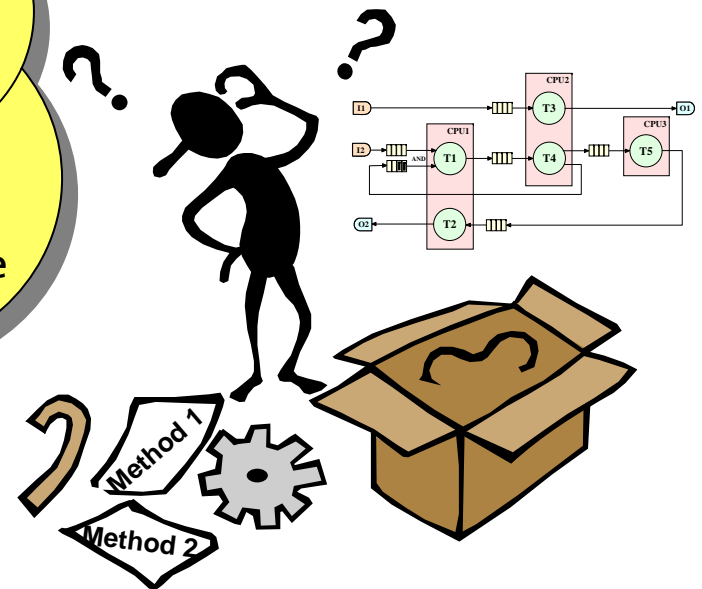
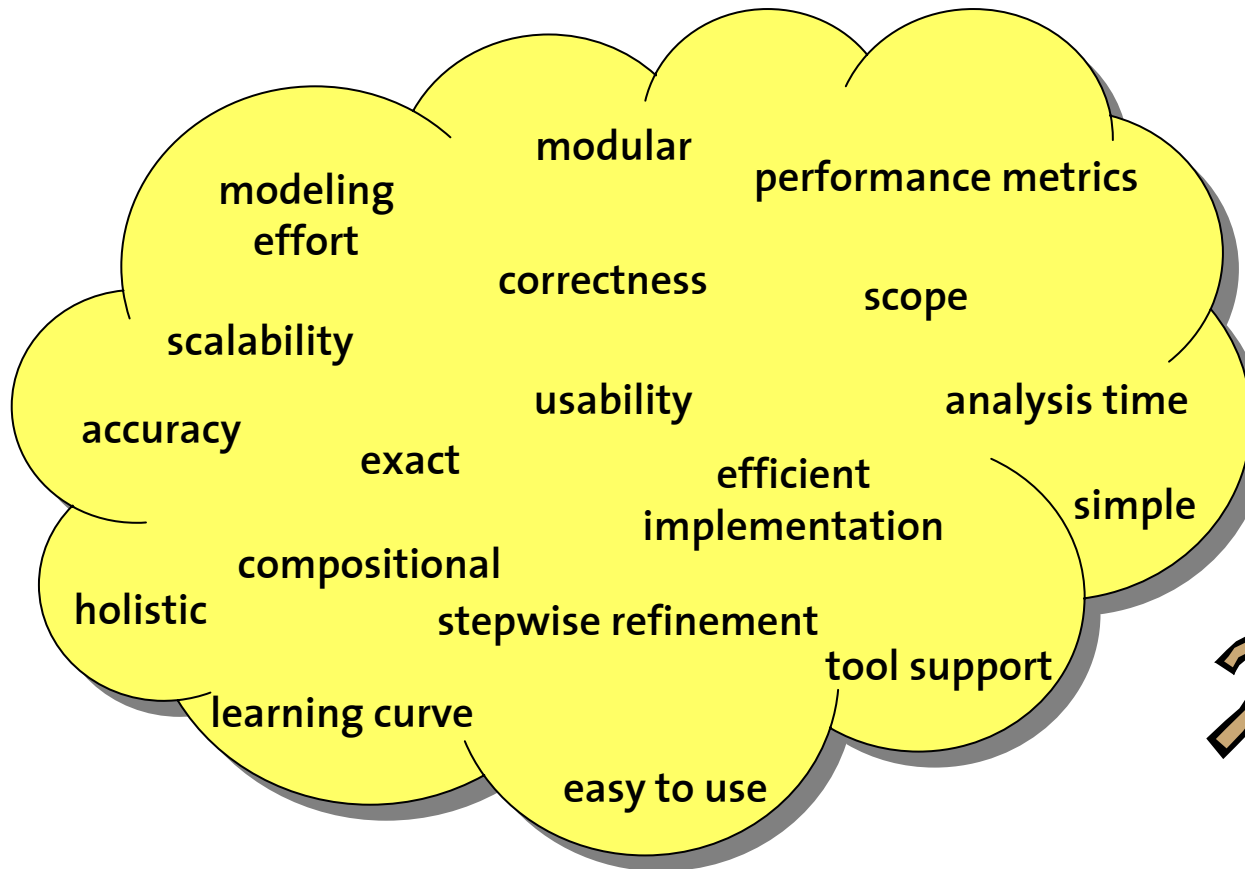
# Motivating questions

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- What is the influence of the different models on the analysis accuracy ?
- Does abstraction matter ?
- Which abstraction is best suited for a given system ?

Evaluation and comparison of abstractions is needed !

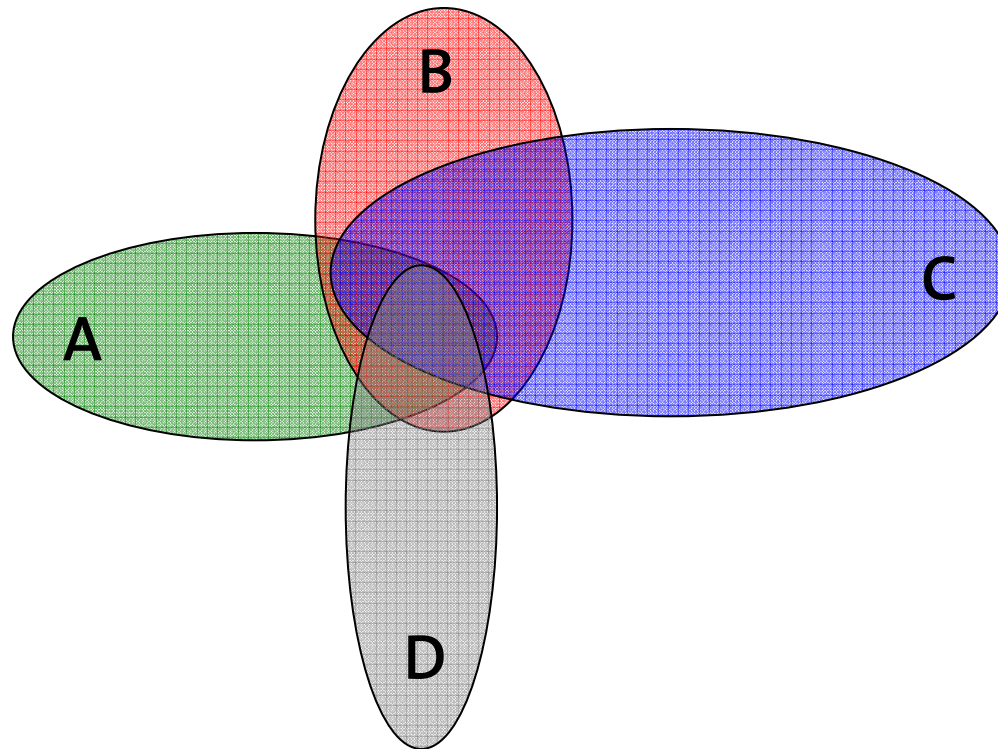
# How can we compare different abstractions ?



# What makes a direct comparison difficult?

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- Many aspects can not be quantified
- Models cover different scenarios:



# Intention

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Compare models and methods that analyze the timing properties of distributed systems:

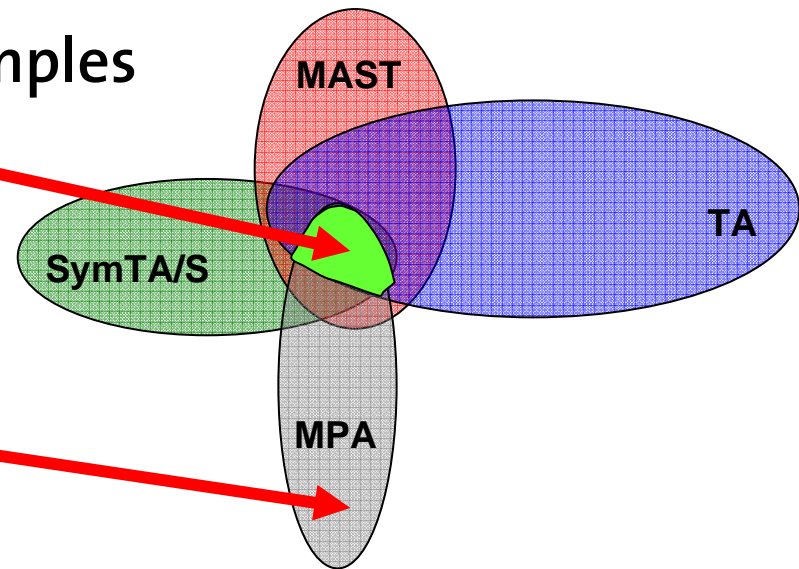
- SymTA/S [Richter *et al.*]
- MPA-RTC [Thiele *et al.*]
- MAST [González Harbour *et al.*]
- Timed automata based analysis [Yi *et al.*]
- ...



# Approach

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- Leiden Workshop on Distributed Embedded Systems:  
<http://www.tik.ee.ethz.ch/~leiden05/>
- Define a set of benchmark examples that cover common area
- Define benchmark examples that show the power of each method



# Expected (long term) results

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- Understand the modeling power of different methods
- Understand the relation between models and analysis accuracy
- Improve methods by combining ideas and abstractions

# Contributions

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- We define a **set of benchmark systems** aimed at the evaluation of performance analysis techniques
- We apply different analysis methods to the benchmark systems and compare the results obtained in terms of **accuracy** and **analysis times**
- We point out several **analysis difficulties** and investigate the **causes** for deviating results

# Outline

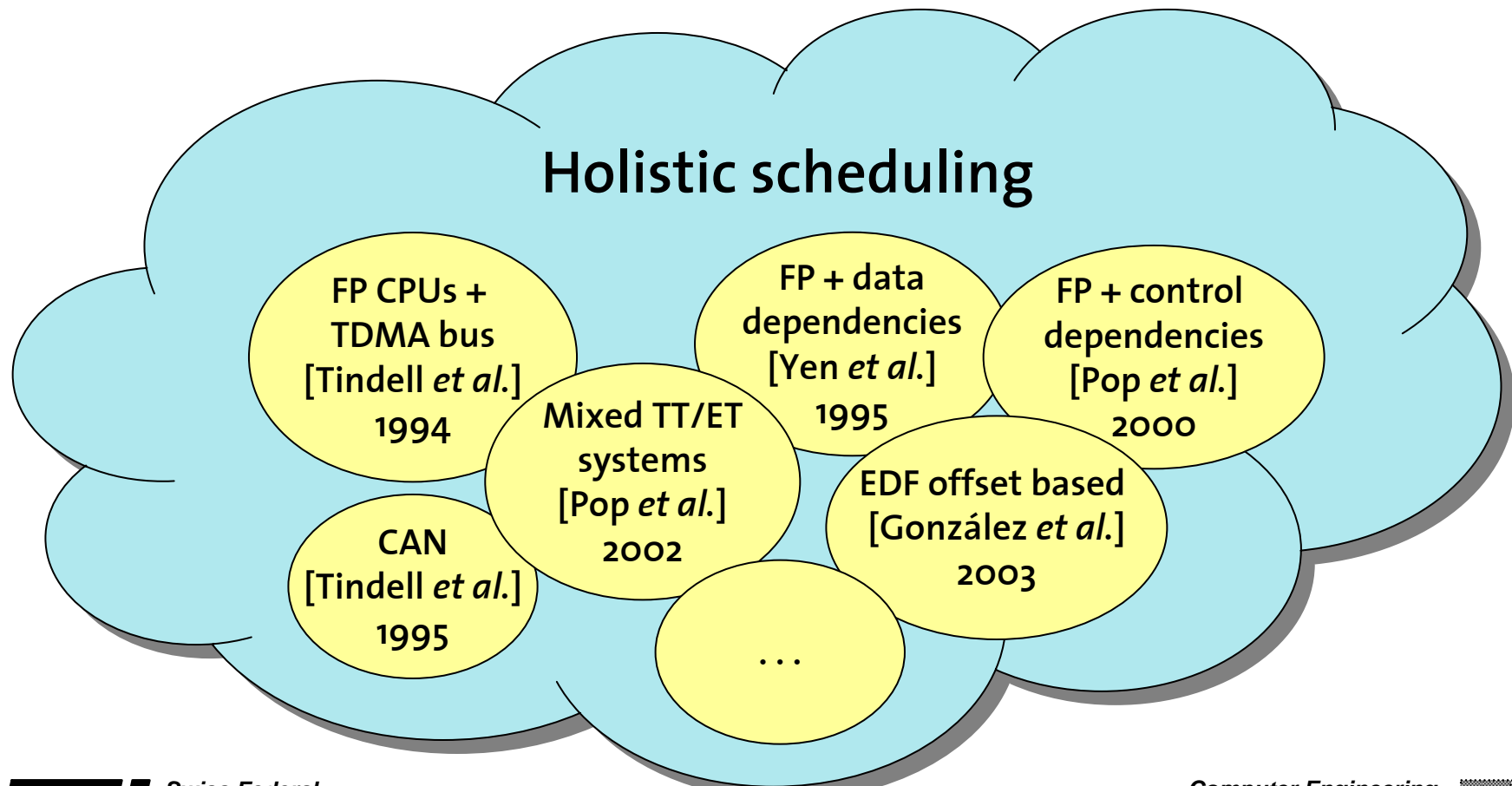
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- Motivation
- Abstractions
- Benchmarks
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# Abstraction 1 - Holistic scheduling

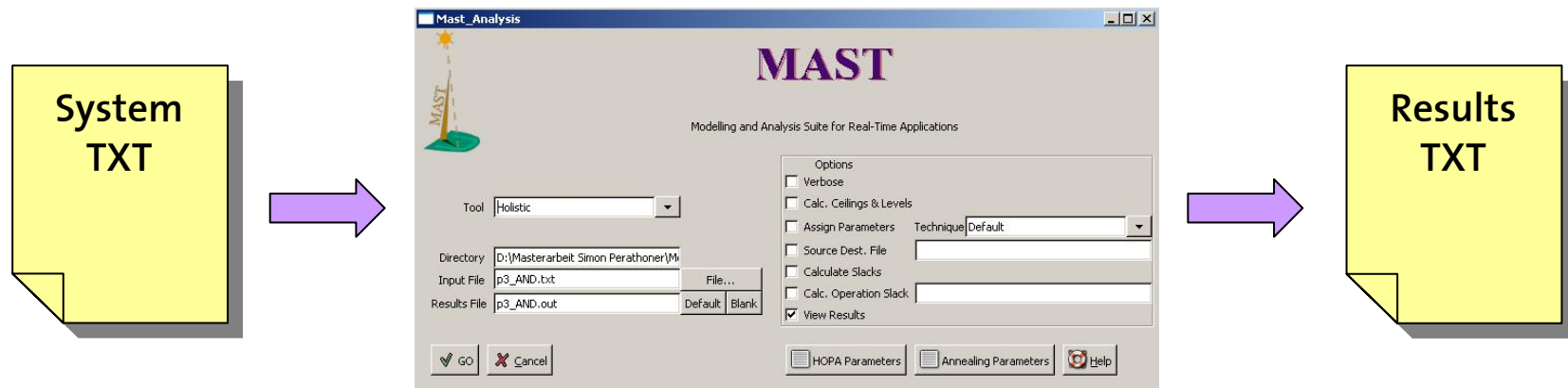
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Basic concept: extend concepts of classical scheduling theory to distributed systems



# Holistic scheduling – MAST tool

MAST - The Modeling and Analysis Suite for Real-Time Applications [González Harbour *et al.*]



# Abstraction 2 – The SymTA/S approach

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Basic concept: Application of classical scheduling techniques at resource level and propagation of results to next component

Problem: The local analysis techniques require the input event streams to fit given standard event models



Solution: Use appropriate interfaces: EMIFs & EAFs

# SymTA/S – Tool



The screenshot displays the SymTA/S software interface. The main window shows a task graph with nodes for sources (S0, S1), tasks (T0, T1), and CPUs (CPU0, CPU1) connected by events (E0-E5). A Gantt chart for CPU0 shows the execution of tasks T0 and T1, with a yellow bar for T0 (duration 2) and a red bar for T1 (duration 4). The console window shows the following output:

```

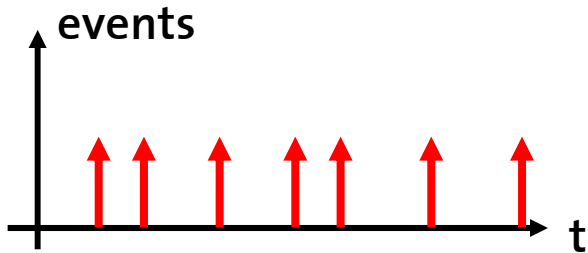
12:10:01 Global analysis step started on [CPU0, CPU1, Bus0]
12:10:01 Analysis on CPU0 started ...
12:10:01 Performing Global Offset Sensitive Analysis
12:10:01 Critical instant determined by T0
12:10:01 WC resp time for activation 1 of T0: 2
12:10:01 Critical instant determined by T0
12:10:01 WC resp time for activation 1 of T1: 5
12:10:01 Critical instant determined by T1
12:10:01 WC resp time for activation 1 of T1: 4
12:10:01 Global Offset Sensitive Analysis complete (125ms).
12:10:01 Analysis on CPU0 finished.
12:10:01 Global analysis step finished.
12:10:01 EventModel-propagation started on [CPU0]
12:10:01 EventModel-propagation finished.
12:10:01 Global Analysis successfully finished after 7 updates and 5 iterations (1000ms).
    
```

The right-hand side of the interface contains several configuration panels:

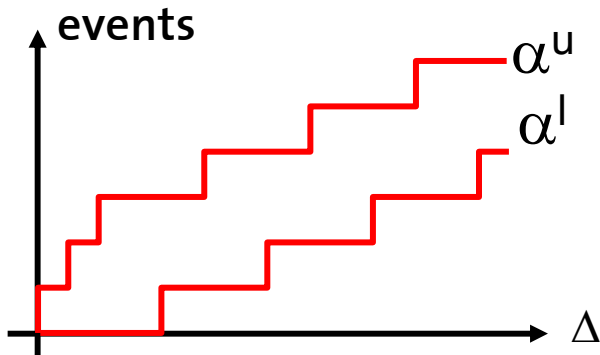
- Tasks:** Shows task list T1 on CPU0. Core Task Time is 4. Response Time is 4. Output Event Model is P (10) + J (1). Scheduling is Static Priority Preemptive.
- Resources:** Shows resource list CPU0. Speed factor is 1.0. Scheduling is Static Priority Preemptive. Utilisation is 20%.
- Event Streams:** Shows event stream list E5. Output Assertion is P (10) + J (1). Actual Input is P (10) + J (1). Target Requirement is any.



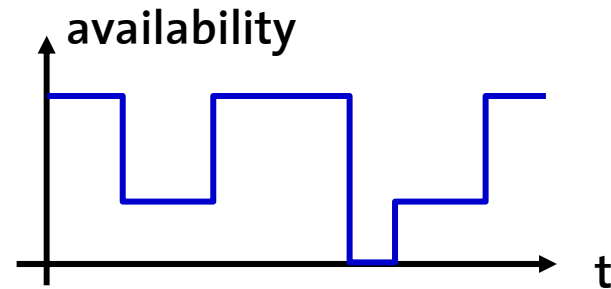
# Abstraction 3 – MPA-RTC



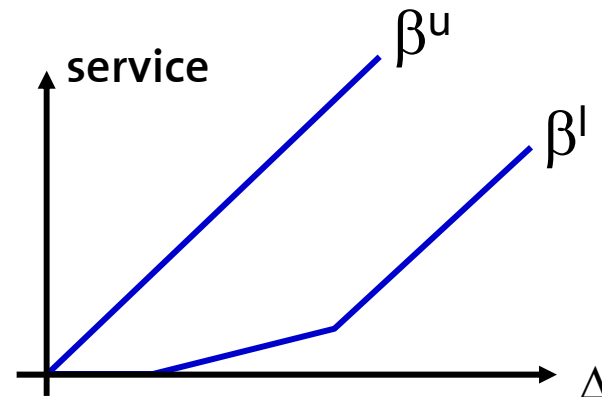
↓ Load model



Arrival curves

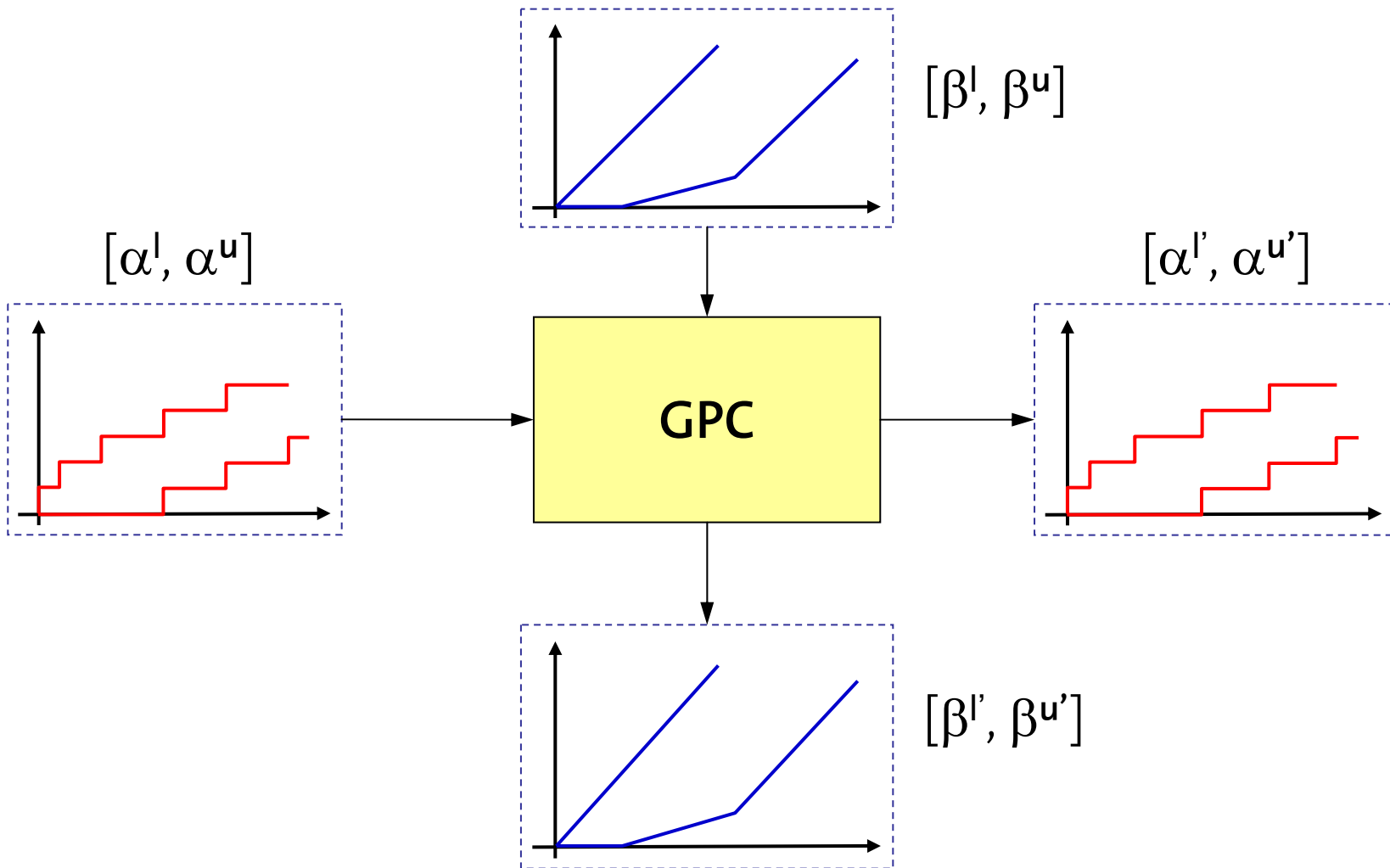


↓ Service model

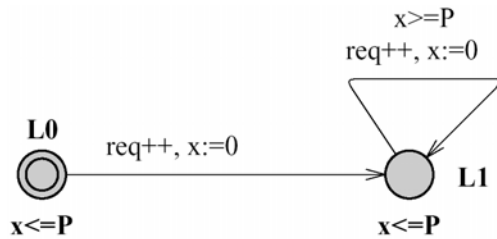


Service curves

# Abstraction 3 – MPA-RTC



# Abstraction 4 - TA based performance analysis

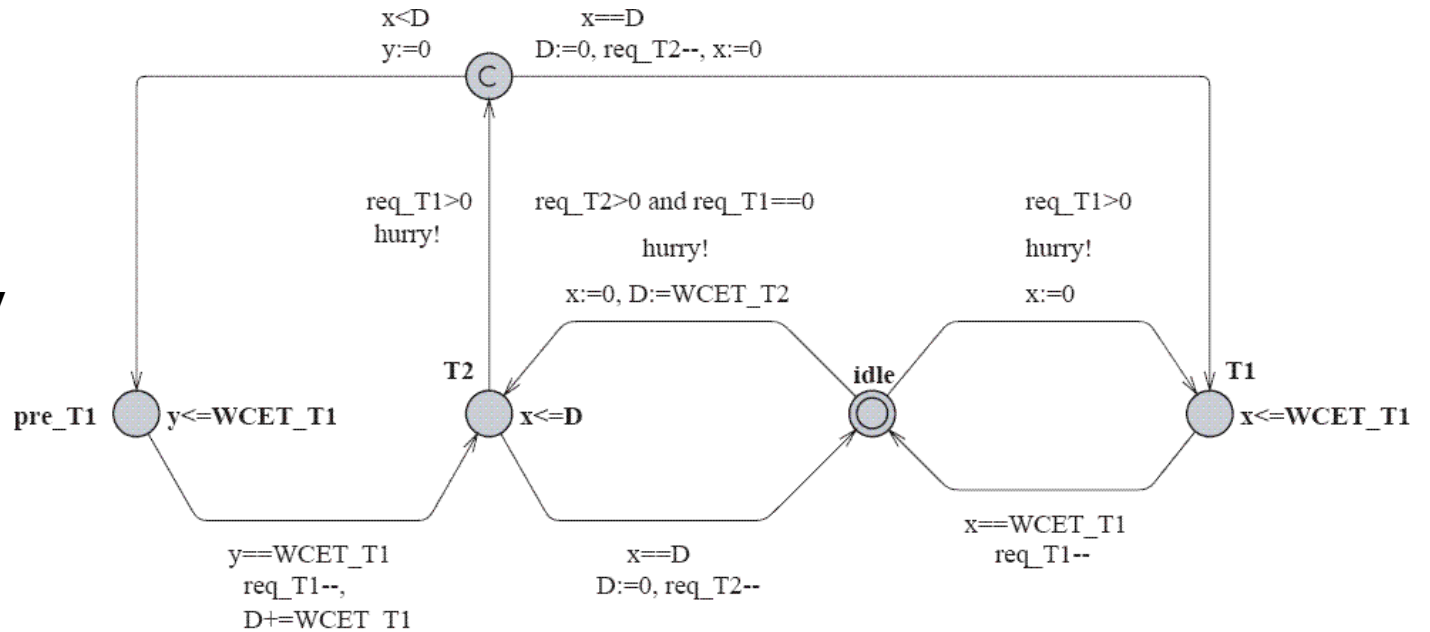


periodic stream

Verification of performance properties by model checking (UPPAAL)

Exact performance values

fixed priority scheduling



# Outline

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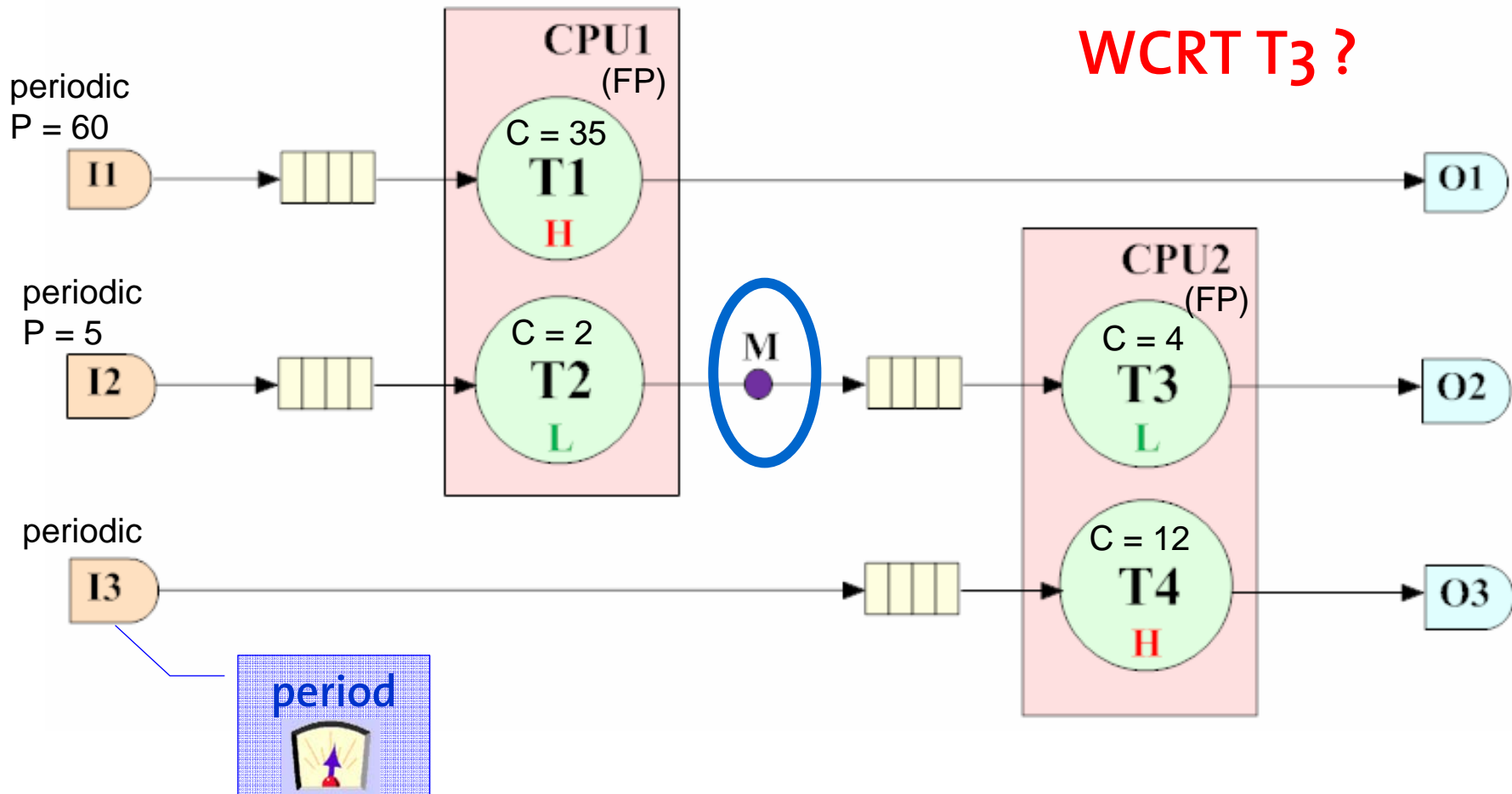
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# Benchmarks

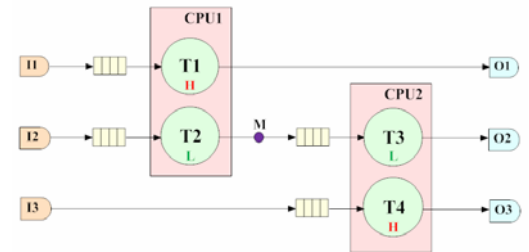
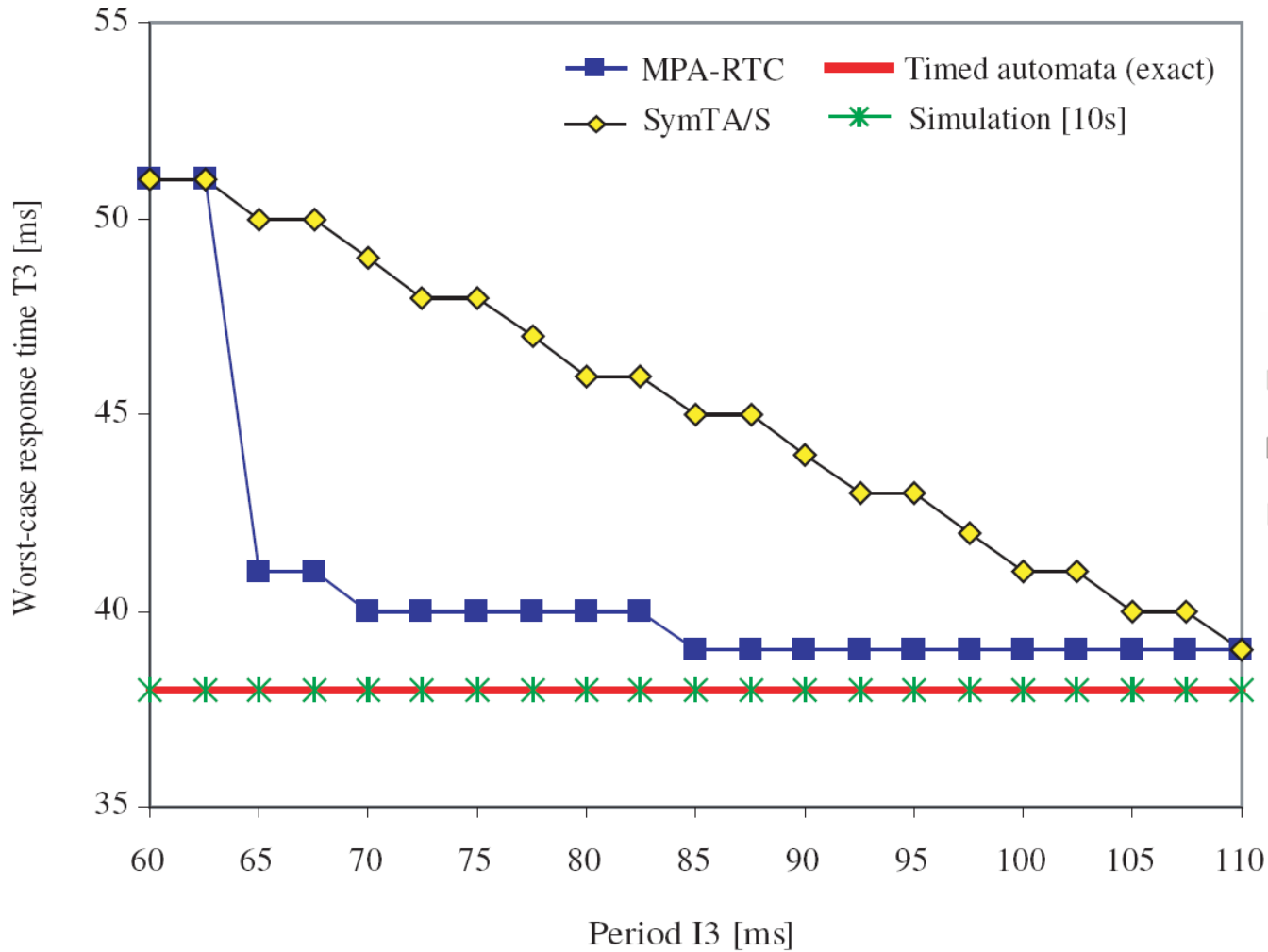
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- Pay burst only once
- Complex activation pattern
- Variable feedback
- Cyclic dependencies
- AND/OR task activation
- Intra-context information
- Workload correlation
- Data dependencies

# Benchmark 1 – Complex activation pattern

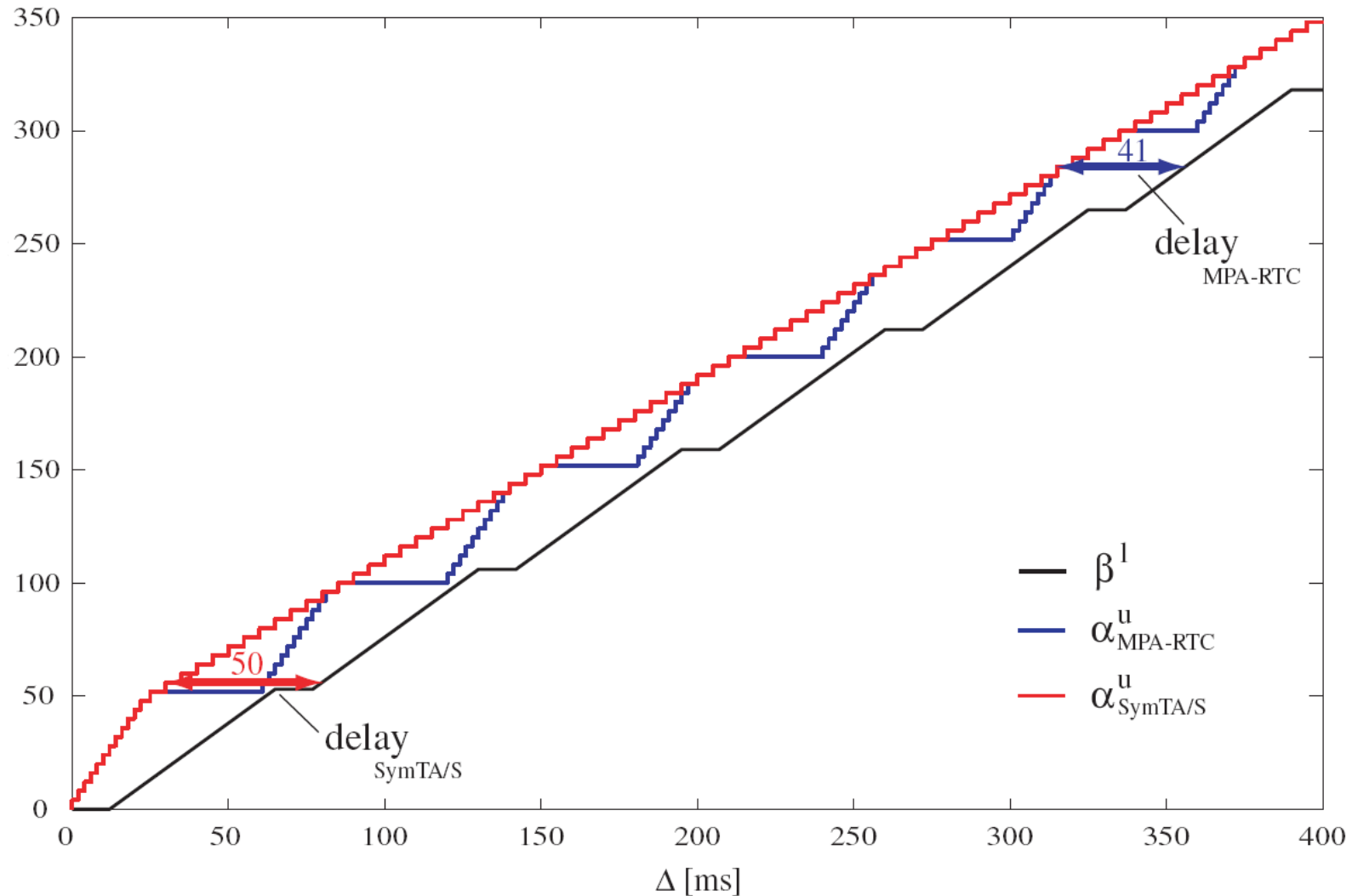


# Benchmark 1 – Analysis results



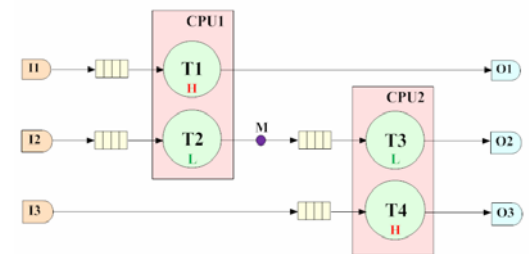
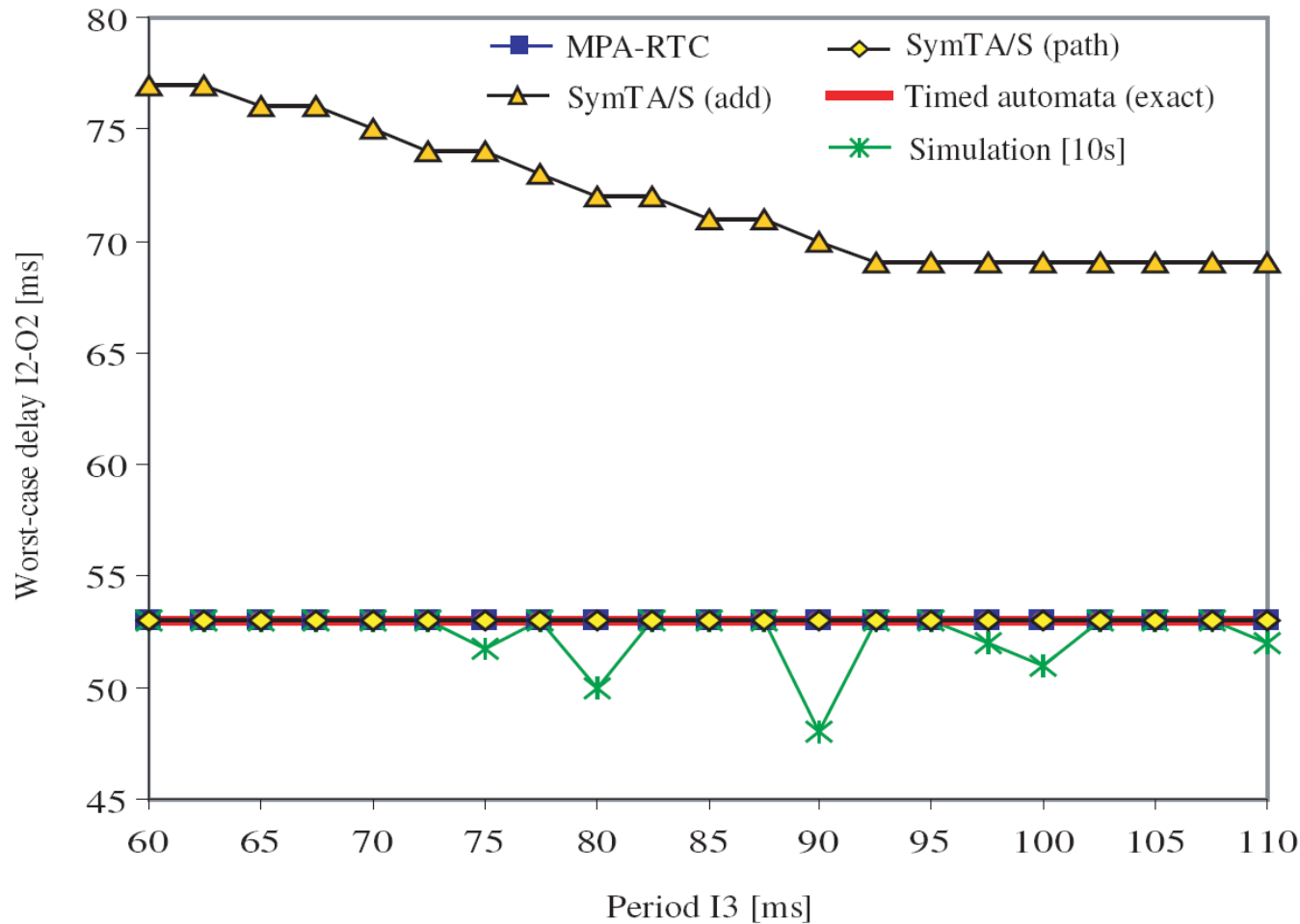
# Benchmark 1 – Result interpretation

$P_{13} = 65 \text{ ms}$

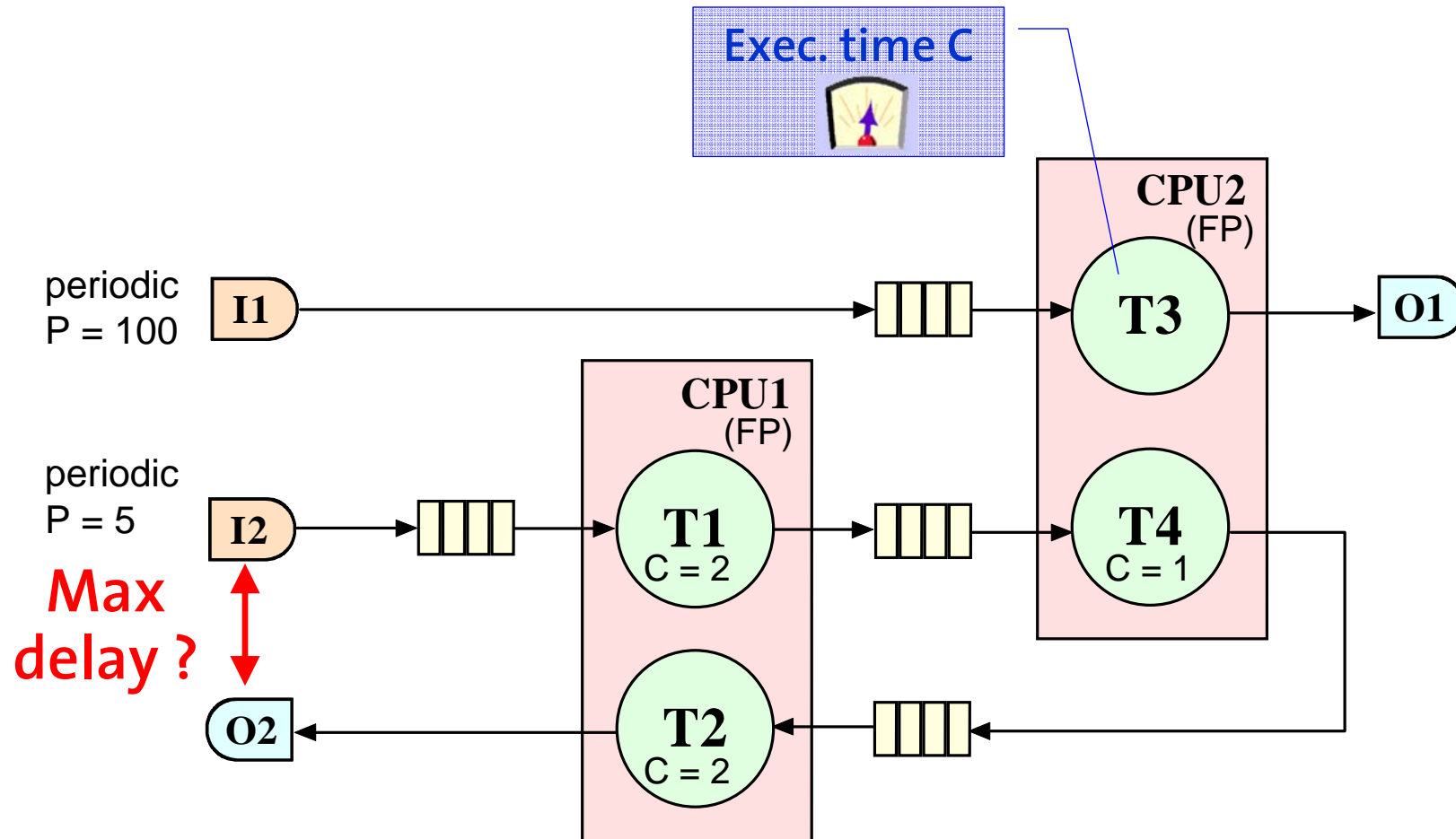




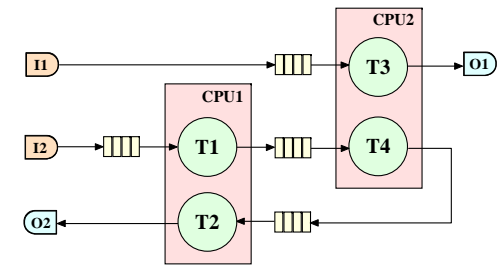
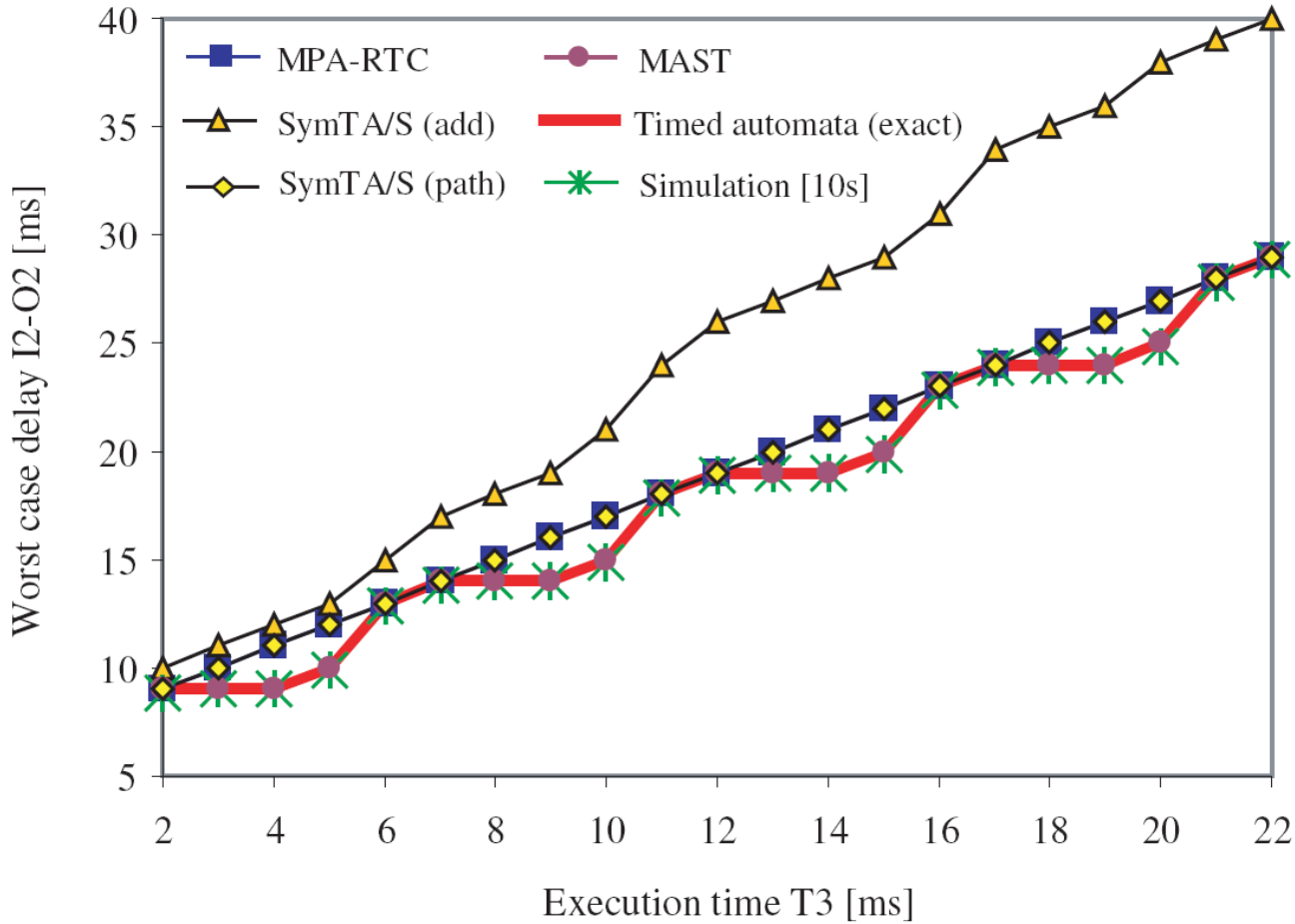
# Benchmark 1 – Worst case Delay I2-O2



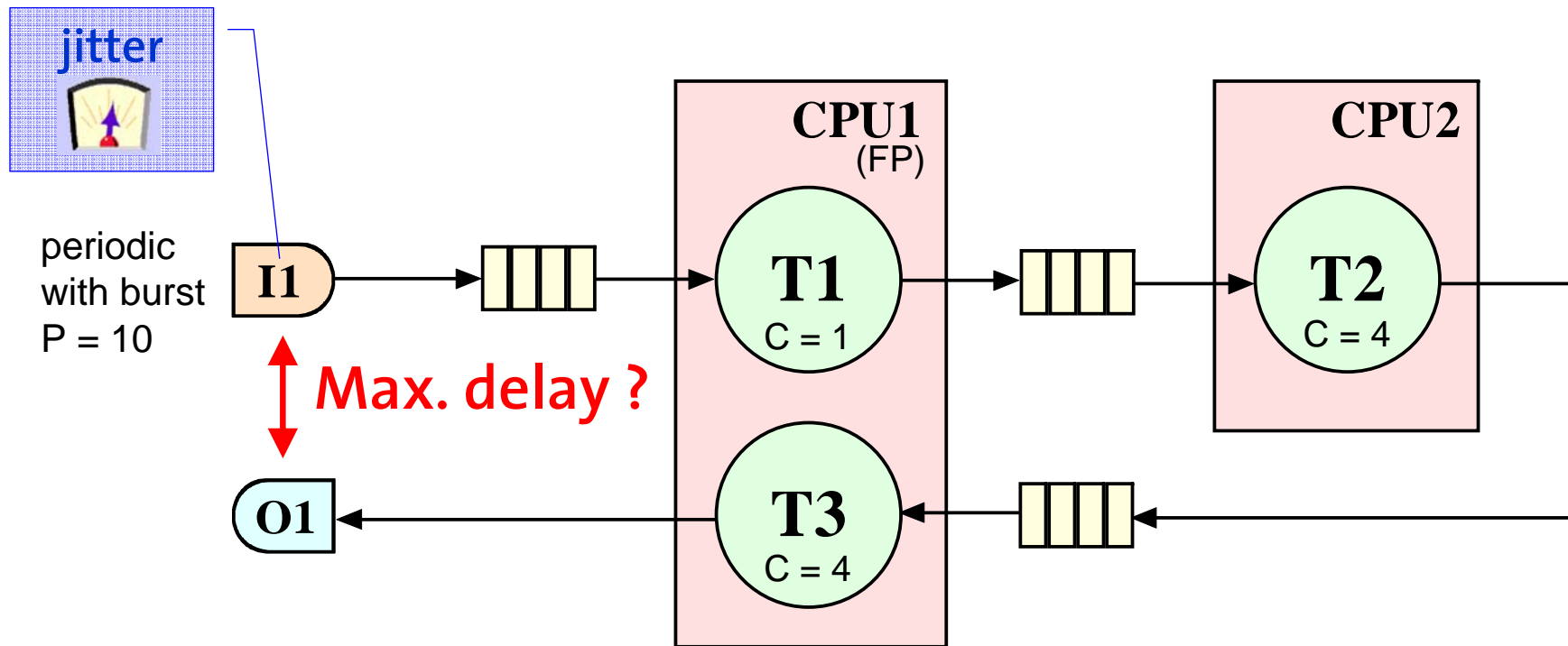
# Benchmark 2 – Variable feedback



# Benchmark 2 – Analysis results

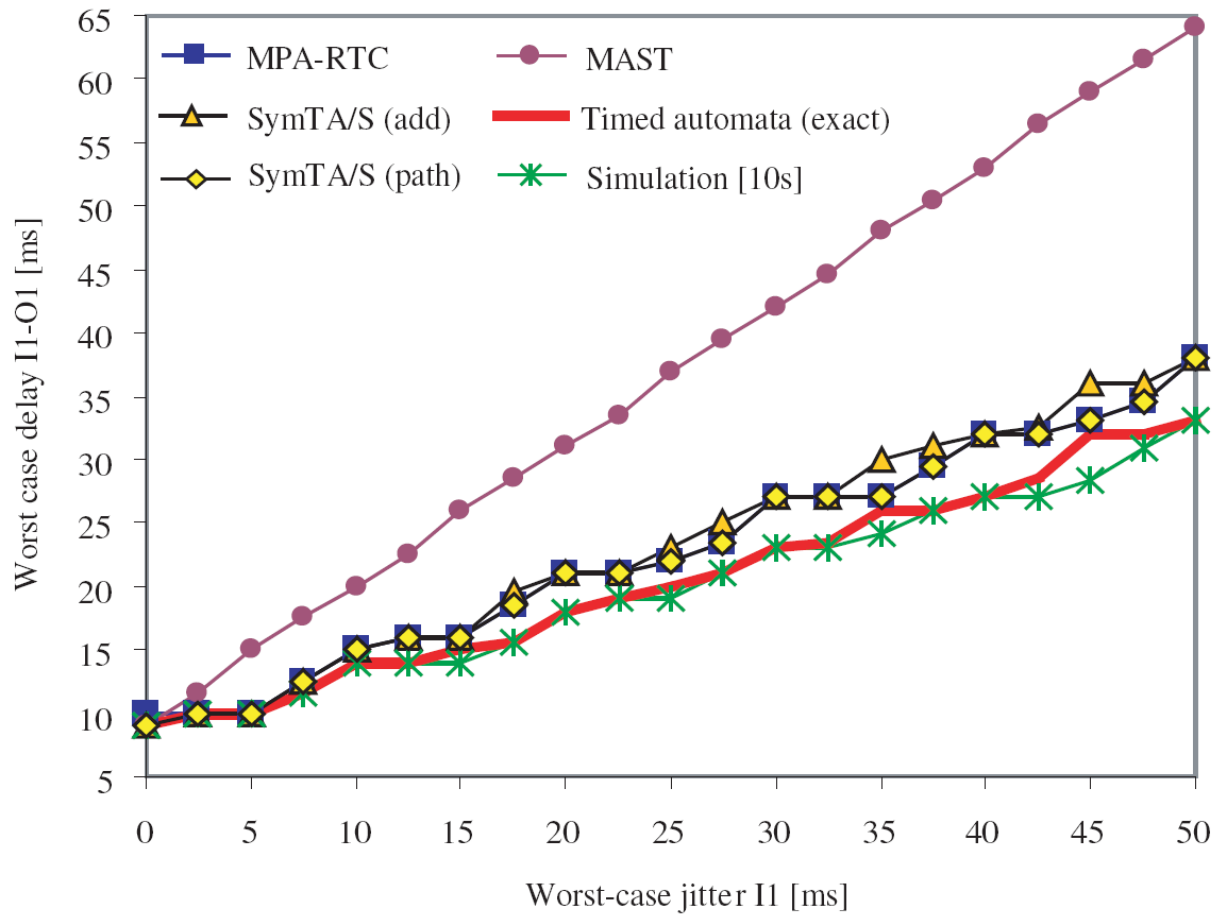
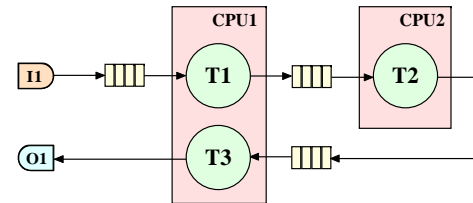


# Benchmark 3 – Cyclic dependencies



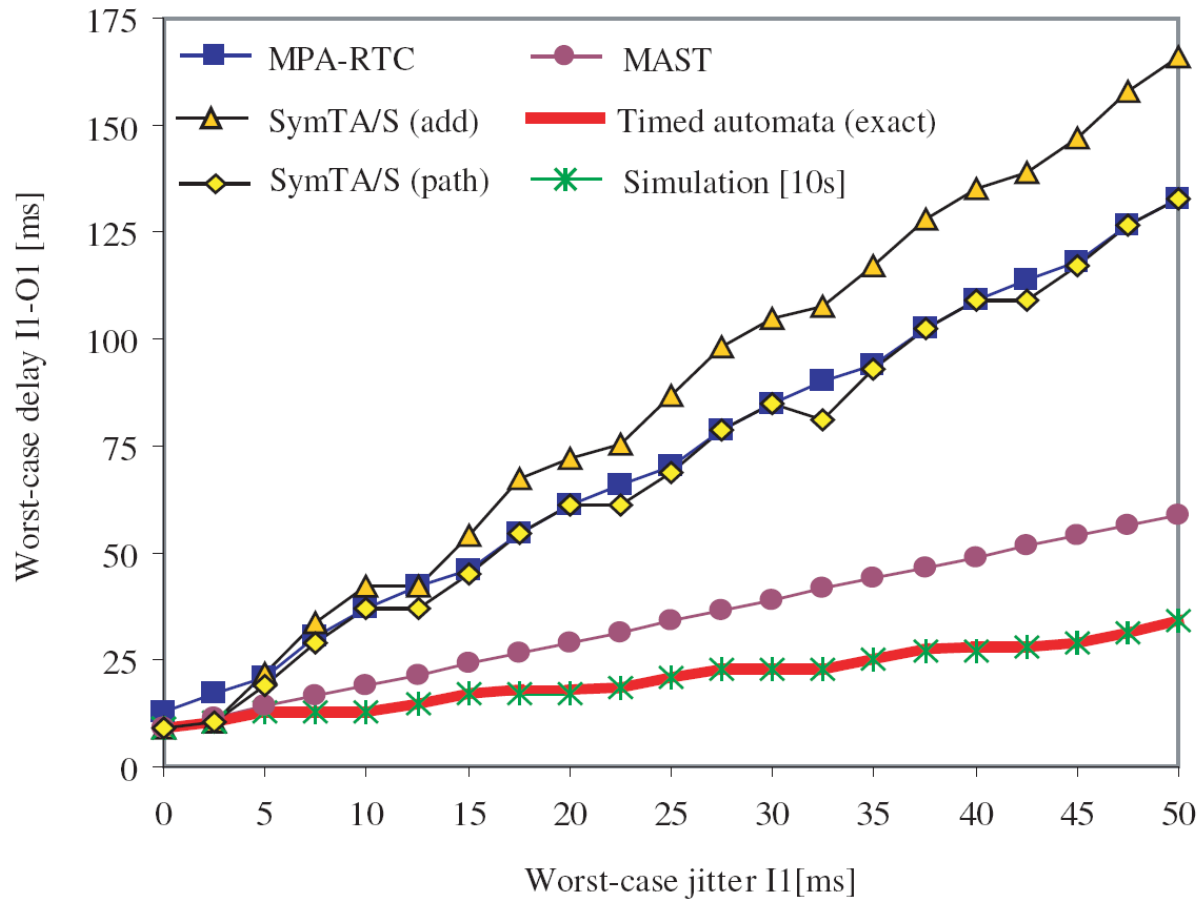
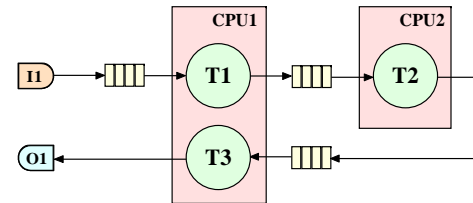
# Benchmark 3 – Analysis results

Scenario 1: priority T1 = high  
priority T3 = low



# Benchmark 3 – Analysis results

Scenario 2: priority T1 = low  
priority T3 = high



# Analysis times [s]

		B1	B2	B3 (sc.1)	B3 (sc.2)	B4
MPA-RTC	min	0.60	0.03	0.01	0.04	0.03
	med	1.06	0.04	0.01	0.15	0.05
	max	19.72	0.08	0.04	0.30	0.20
SymTA/S	min	0.05	0.03	0.03	0.03	0.06
	med	0.09	0.05	0.06	0.34	0.09
	max	1.50	0.23	0.09	0.80	0.31
MAST	min	-	< 0.5	< 0.5	< 0.5	< 0.5
	med	-	< 0.5	< 0.5	< 0.5	< 0.5
	max	-	< 0.5	< 0.5	< 0.5	< 0.5
Timed aut.	min	18.0	< 0.5	< 0.5	< 0.5	< 0.5
	med	34.5	< 0.5	1.0	< 0.5	< 0.5
	max	60.5	< 0.5	52.0	5.5	< 0.5
Simulation	min	1.0	< 0.5	0.5	0.5	< 0.5
	med	1.0	< 0.5	0.5	0.5	< 0.5
	max	1.0	< 0.5	0.5	0.5	< 0.5

# Outline

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- Motivation
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# Discussion

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- Approximation of complex event streams with **standard event models** can lead to **poor performance predictions** at **local level**
- **Holistic** approaches **better** in the presence of **correlations** among task activations (e.g. data dependencies)
- **Cyclic dependencies** represent a **serious pitfall** for the accuracy of **compositional** analysis methods
- **Holistic** methods **less appropriate** for timing properties referred to the *actual* release time of an event within a large **jitter** interval

# Conclusions

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- The **analysis accuracy** and the analysis time **depend highly on the specific system characteristics**
- **None** of the analysis methods **performed best** in all benchmarks
- The analysis results of the different approaches are **remarkable different** even for apparently basic systems
- The choice of an appropriate analysis **abstraction matters**
- The problem to provide accurate performance predictions for general systems is still **far from solved**

Thank you!

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